

$$\vec{F}_{\text{el}} =$$

$$\vec{F}_{\text{el}} = K(l-y)\hat{j}$$

$$m\vec{y} = -mgy\hat{j}$$

$$m a_y \hat{j} = \vec{F}_{\text{el}} + m\vec{y} \neq 0$$

$$\vec{F}_{\text{el}} + m\vec{y} = 0$$

$$\textcircled{X} \quad a_y = \frac{K}{m}(l-y) - g$$

$$Kl - mg = 0$$

$$\frac{K}{m}l - g = 0$$

$$Kl\hat{j} - mgy\hat{j} = 0$$

$$\frac{d^2 y}{dt^2} = -\frac{K}{m}y + \left(\frac{K}{m}l - g\right) = 0$$

$$\frac{d^2 y}{dt^2} = -\frac{k}{m} y \Rightarrow$$

$$\dot{y}(A) = -\omega A \sin(\omega t + \phi)$$

$$y(t) = A \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$T = \frac{2\pi}{\omega}$$

COND. INIZ.

$$y(0) = y_0 > 0$$

$$y_0 = A \cos \phi$$

$$y_0 = A$$

$$\dot{y} = \frac{dy}{dt} = 0$$

$$0 = -\omega A \sin \phi \Rightarrow$$

$$\phi = 0$$

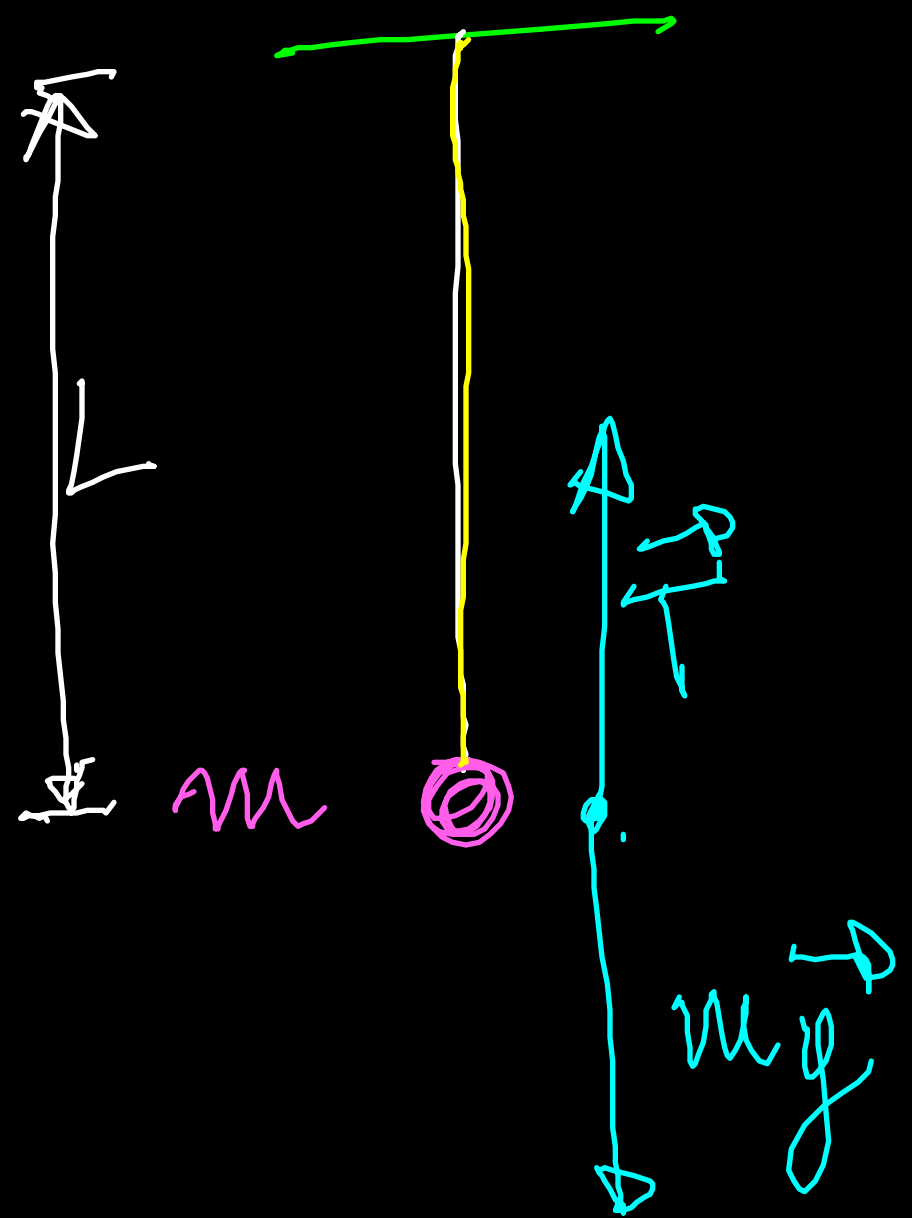
$$y(t) = y_0 \cos \omega t$$

$$\frac{d^2 x}{dt^2} = -\omega^2 x$$

$$\ddot{x} = -\omega^2 x$$

PENDOLO SEMPLICE

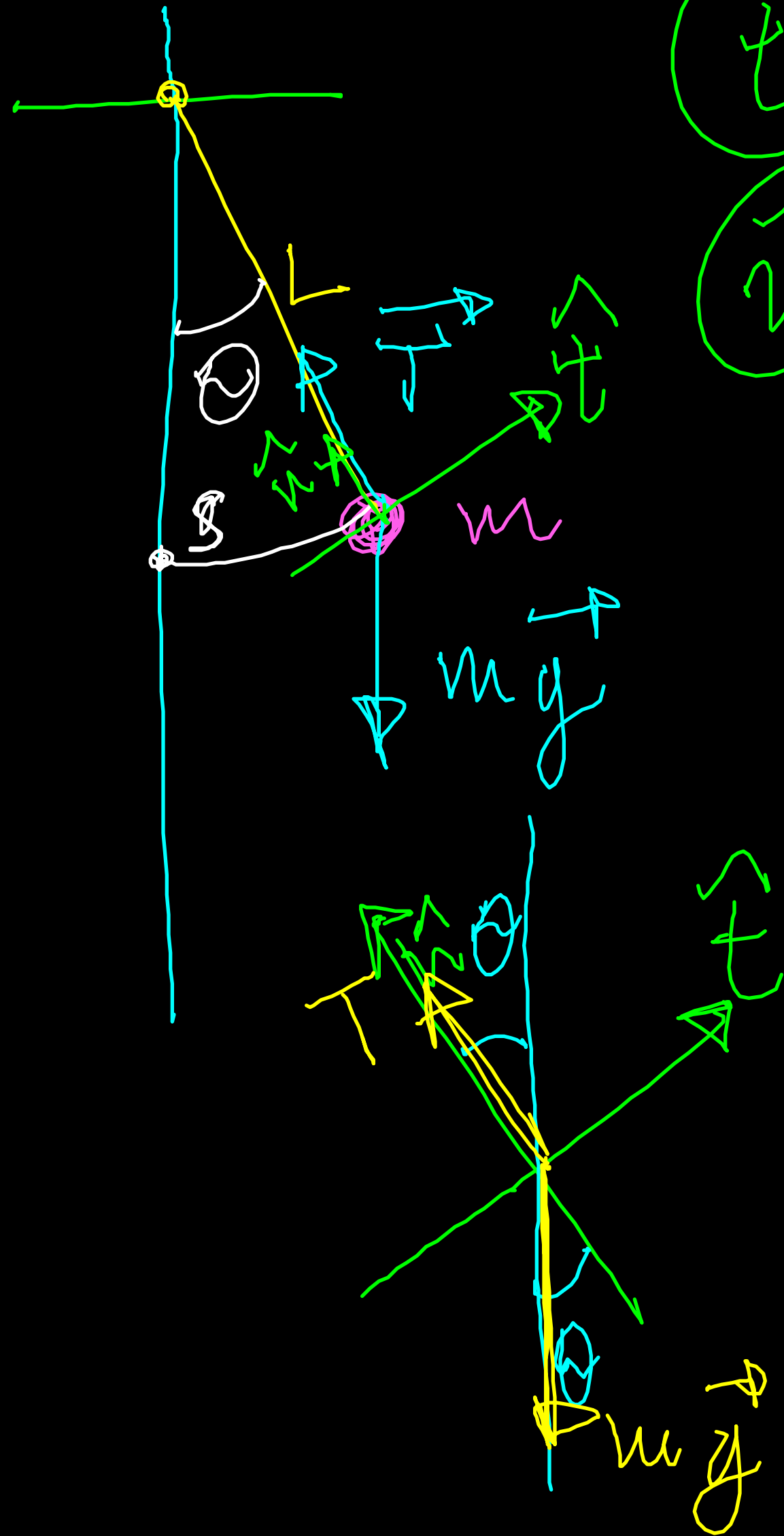
POS. DI EQ.



$$mg \approx T$$

$$a = 0$$

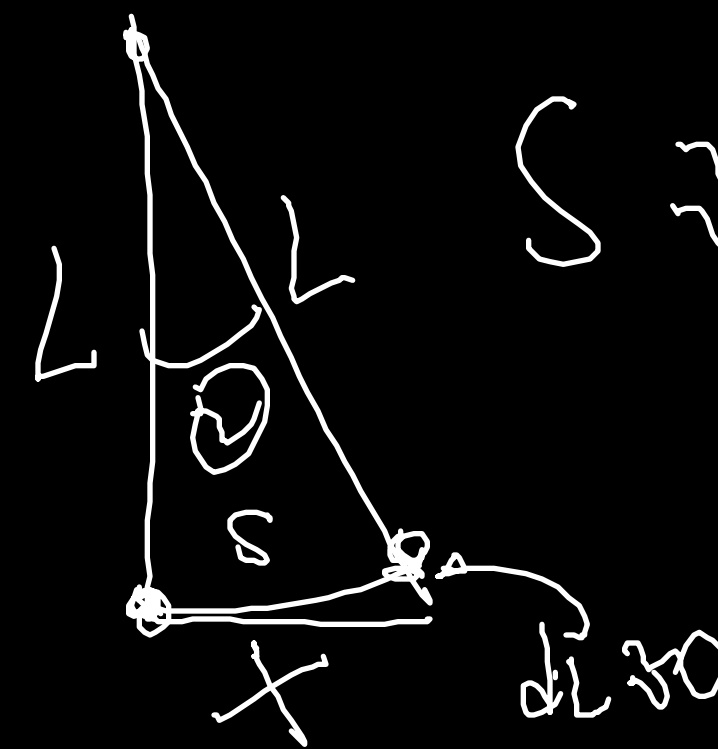
FUORI EQ.



$$-m g \sin \theta = m a_t$$

$$T - m g \cos \theta = 0$$

θ "piccolo", $\theta \ll 1 \text{ rad}$



$$s \approx x$$

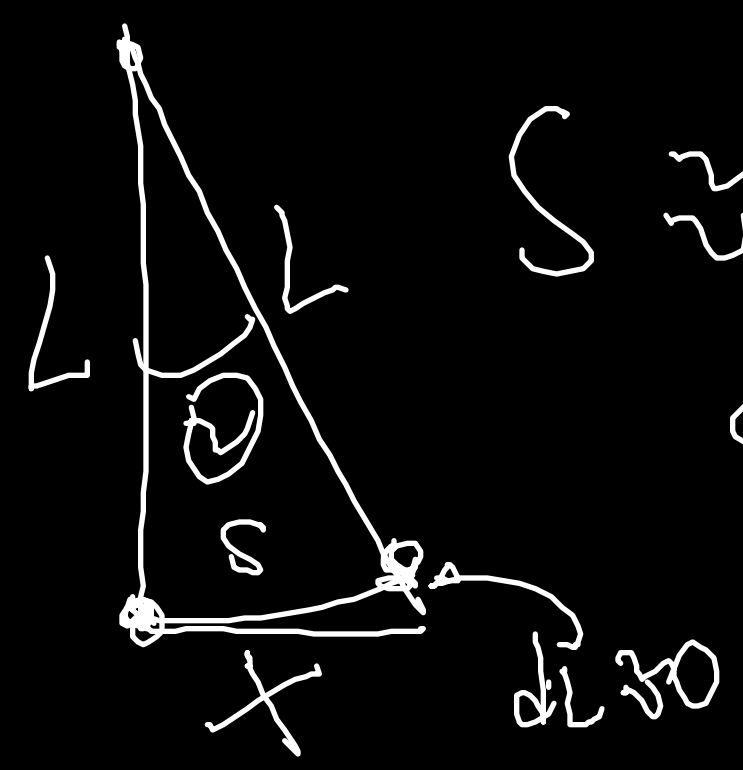
$$\sin \theta = \frac{x}{L}$$

$$a_t \approx a_x$$

$$-m g \sin \theta = m a_t$$

$$T - m g \cos \theta = 0$$

θ "piccolo", $\theta \ll 1$ rad



$S \approx X$
 $\sin \theta = \frac{X}{L}$
 $a_t \approx a_x$

$$m a_x = m \frac{d^2 X}{dt^2} = -m g \frac{X}{L}$$

$$\omega = \sqrt{\frac{g}{L}}$$

$$T_{PB} = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}$$

$$\Delta a_t = a L$$

$$g = \frac{4\pi^2}{T_{PB}^2} L$$

$$-m g \sin \theta = m a_t = \ddot{\theta} L$$

$$\theta \ll 1 \Rightarrow \ddot{\theta} = -\frac{g}{L} \theta(t)$$

$$\theta(t) = A \cos(\omega t + \phi)$$

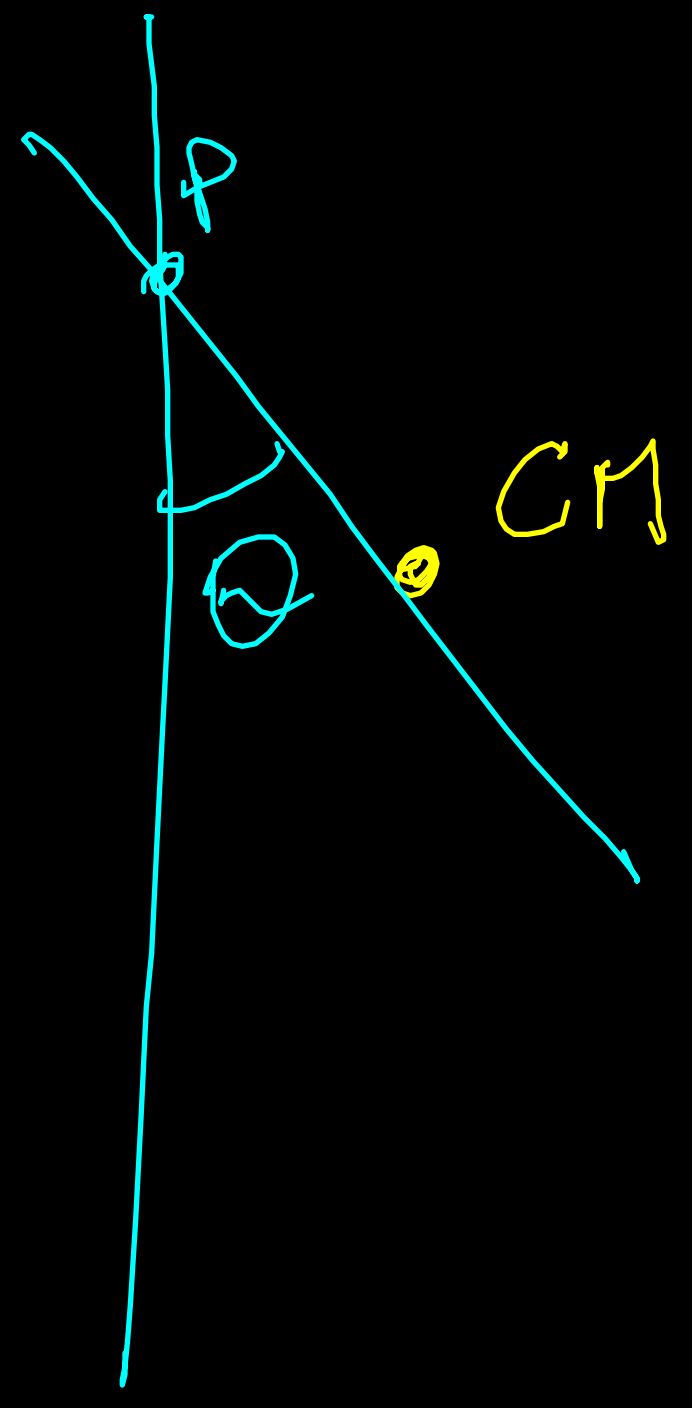
$$\omega = \sqrt{\frac{g}{L}}$$

PENDULO FISICO

$\Delta \theta$



EQ. VIL.



FURTI EQ.

