

SPRINT.

$$\vec{F}_{\text{spring}} = K(l-y) \hat{j}$$

$$m \vec{g} = -m g \hat{j}$$

$$m a_y \hat{j} = \vec{F}_{\text{spring}} + m \vec{g} \neq 0$$

$$\vec{F}_{\text{spring}} + m \vec{g} = 0$$

$$\textcircled{X} \quad a_y = \frac{K}{m} (l - y(t)) - g$$

$$Kl - mg = 0$$

$$\frac{K}{m} l - g = 0$$

$$Kl \hat{j} - mg \hat{j} = 0$$

$$\frac{d^2 y}{dt^2} = -\frac{K}{m} y + \left( \frac{K}{m} l - g \right) = 0$$

$$\frac{d^2 y}{dt^2} = -\frac{k}{m} y \Rightarrow$$

$$\dot{y}(A) = -\omega A \sin(\omega t + \phi)$$

$$y(t) = A \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$T = \frac{2\pi}{\omega}$$

COND. INIZ.

$$y(0) = y_0 > 0$$

$$y_0 = A \cos \phi$$

$$y_0 = A$$

$$\dot{y} = \frac{dy}{dt} = 0$$

$$0 = -\omega A \sin \phi \Rightarrow$$

$$\phi = 0$$

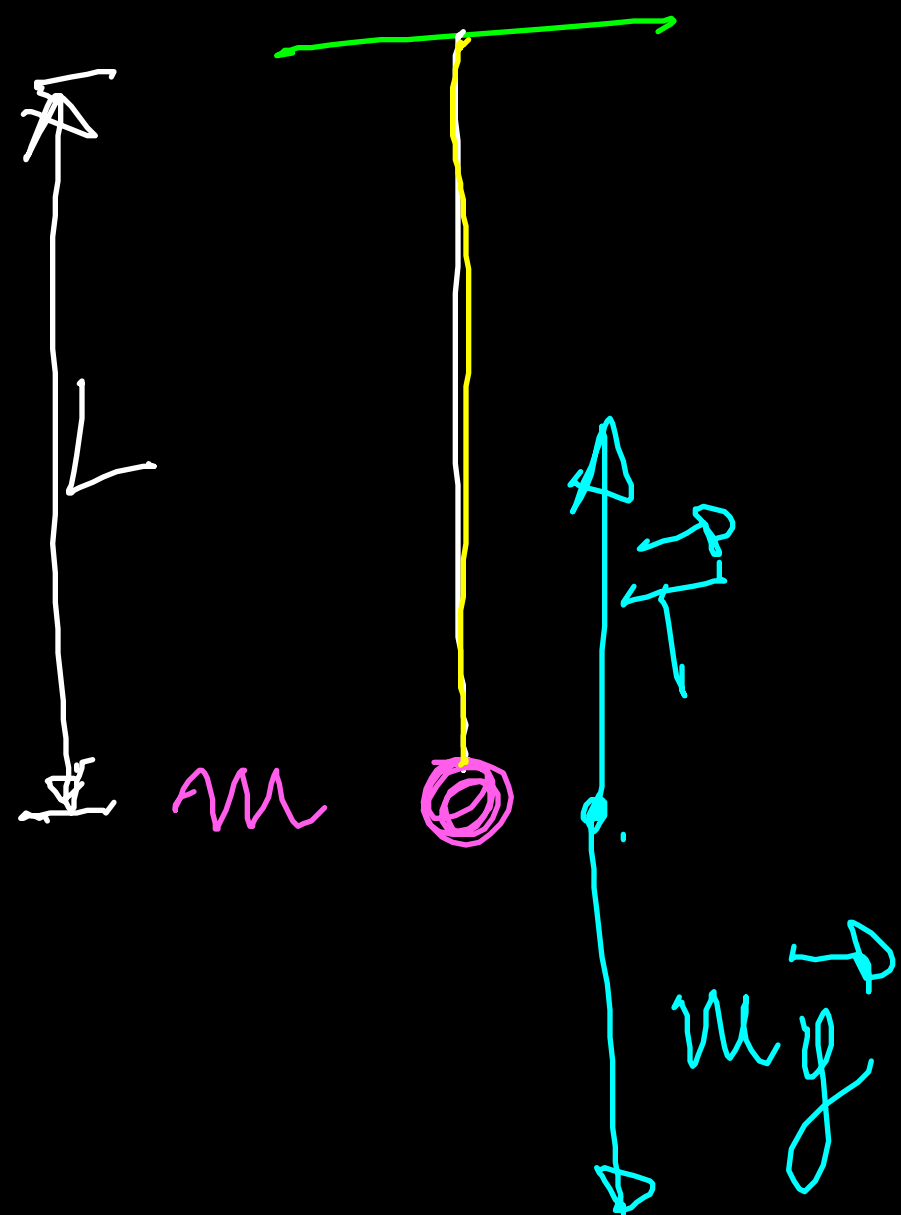
$$y(t) = y_0 \cos \omega t$$

$$\frac{d^2 x}{dt^2} = -\omega^2 x$$

$$\ddot{x} = -\omega^2 x$$

# PENDOLO SEMPLICE

POS. DI EQ.



$$mg \approx T$$

$$Q \approx 0$$

FUORI EQ.

