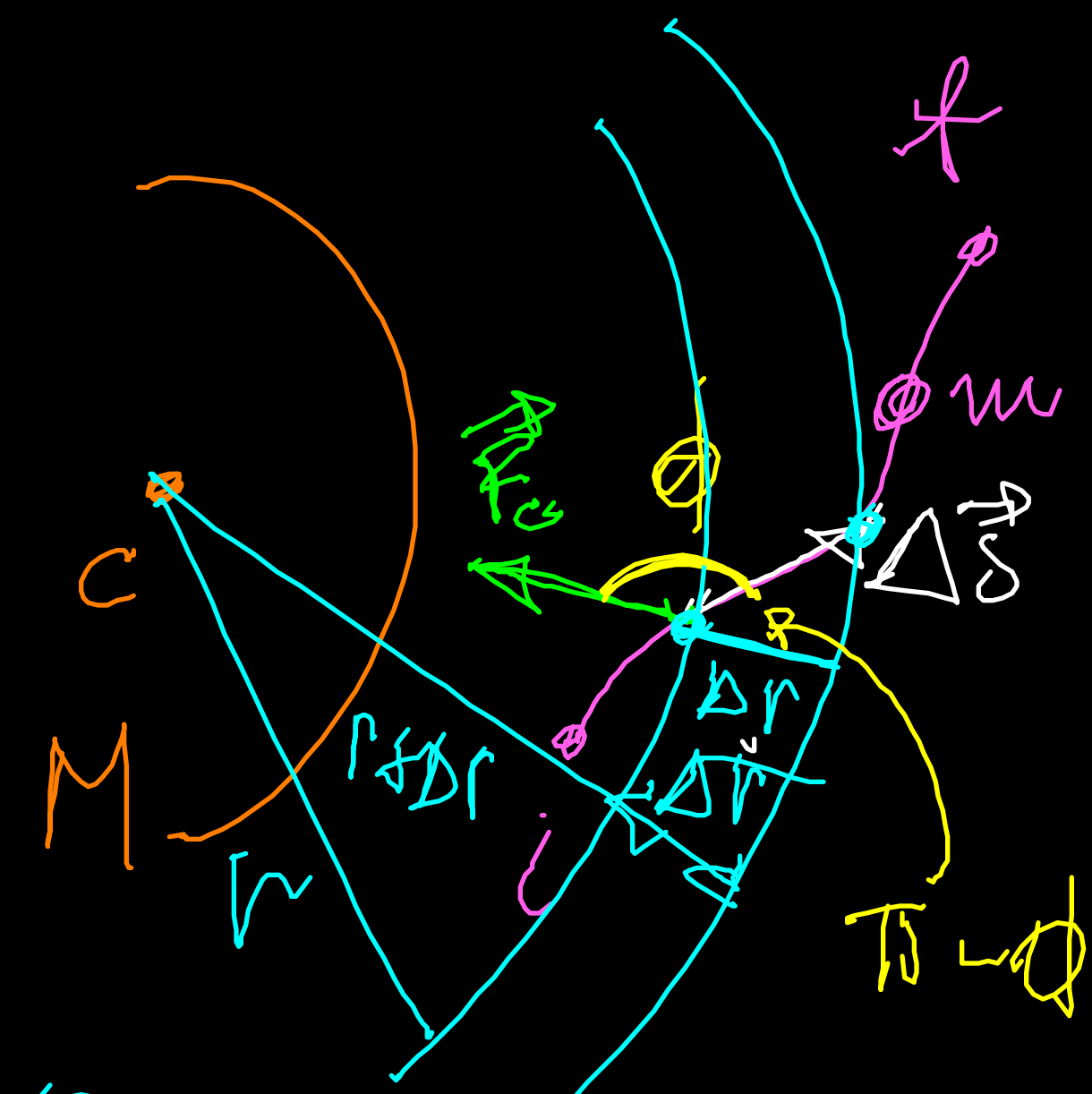


FORZA GRAVITAZIONALE

→ EN. POTENZIALE

$$L_{imp} = \int_i^f \vec{F}_G \cdot d\vec{s}$$

è indep. del percorso?



$$|\Delta \vec{s}| \cos(\pi - \phi) = \Delta r = -|\Delta \vec{s}| \cos \phi$$

$$\begin{aligned} \Delta \vec{s} &\rightarrow d\vec{s} \\ \Delta r &\rightarrow dr \end{aligned}$$

$$dr = -|d\vec{s}| \cos \phi$$

$$\vec{F}_G \cdot d\vec{s}$$

$$= |\vec{F}_G| |d\vec{s}| \cos(\pi - \phi) = -|\vec{F}_G| dr$$

$$|\vec{F}_G| = \frac{GMm}{r^2}$$

→ $\vec{F}_G \rightarrow \infty$

$$L_{imp} = \int_{r_1}^{r_2} \frac{GMm}{r^2} dr$$

$$= \int_{r_1}^{r_2} \frac{GMm}{r^2} dr$$

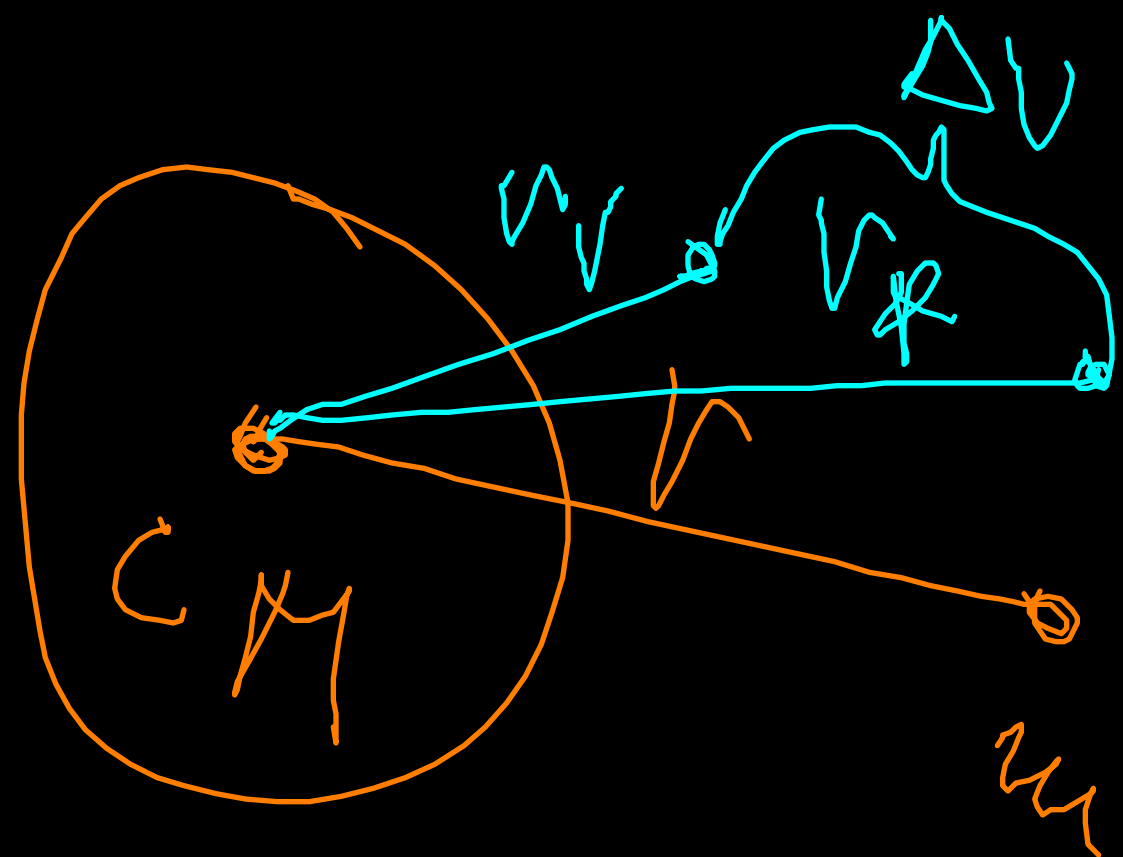
(5)

$$(U_{G, f} - U_{G, i}) = -\int_{i \rightarrow f} \frac{GMm}{r^2} dr = GMm \int_{r_i}^{r_f} \frac{dr}{r^2}$$

$$\frac{d}{dr} \left(-\frac{1}{r} \right) = \frac{1}{r^2}$$

$$= GMm \left[-\frac{1}{r} \right]_{r_i}^{r_f} = -GMm \left[\frac{1}{r_f} - \frac{1}{r_i} \right]$$

$$U_{G, f} - U_{G, i} = - \left(\frac{1}{r_f} - \frac{1}{r_i} \right) GMm \rightarrow U(r) = -\frac{GMm}{r}$$



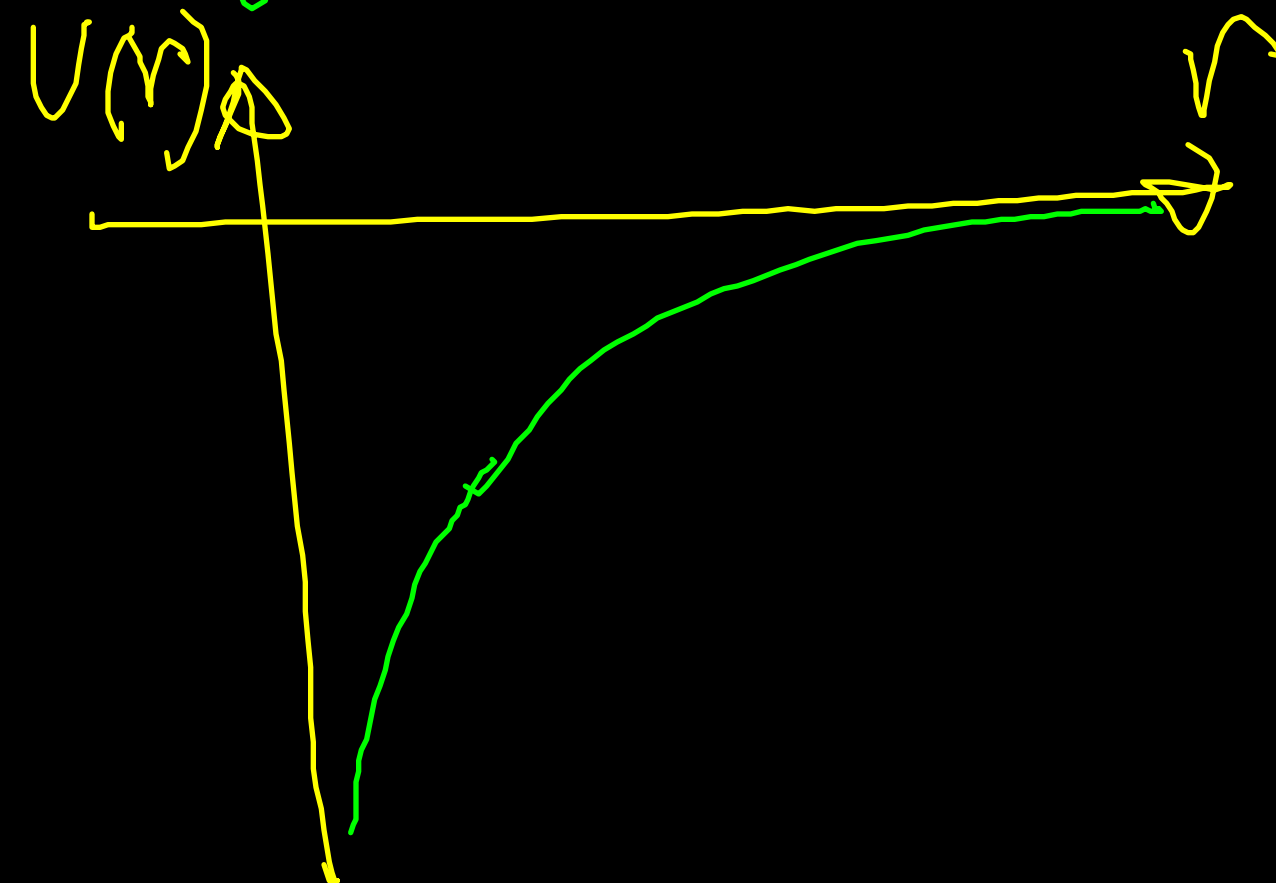
$$U(\infty) = 0$$

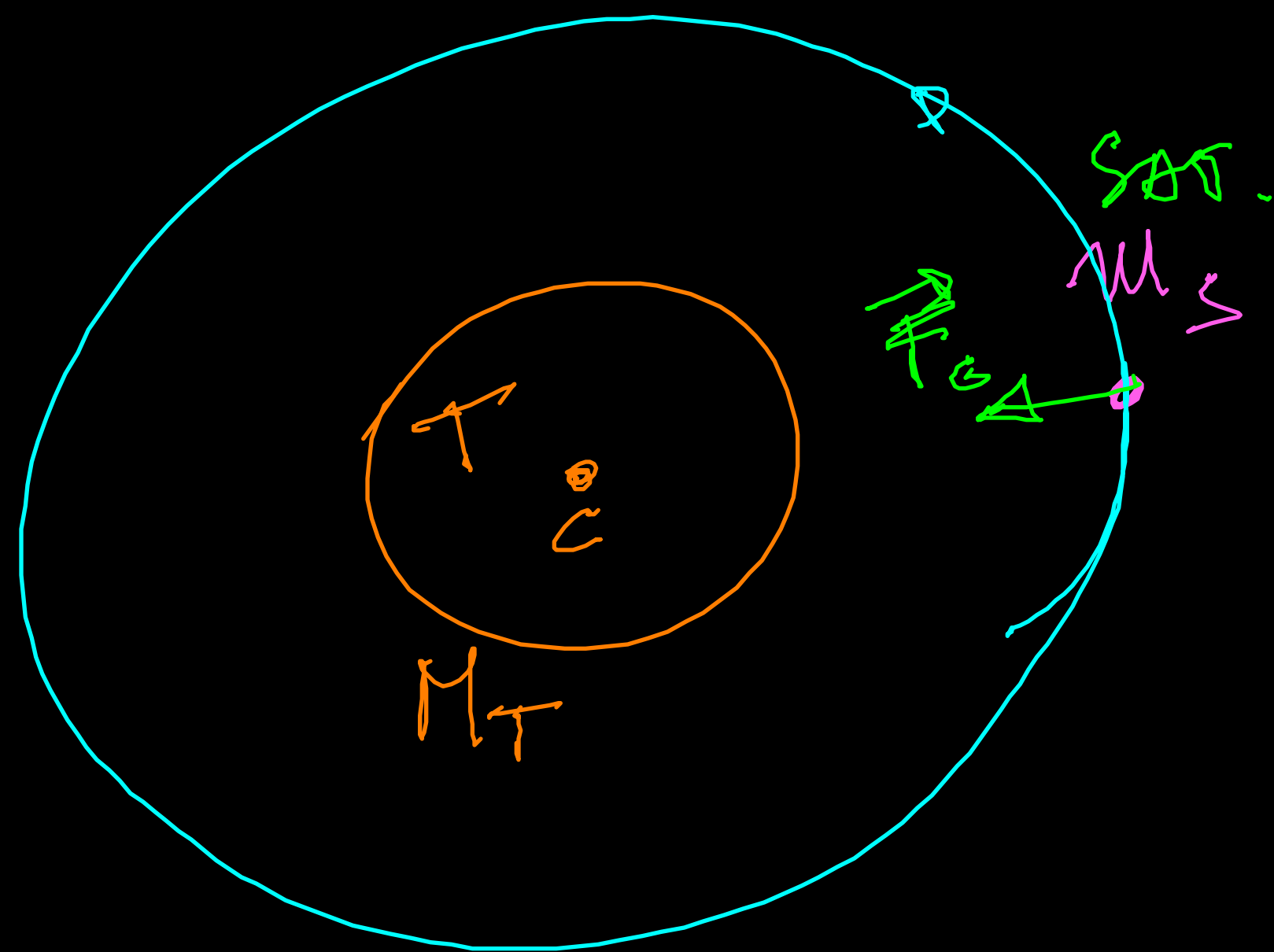
$$r \rightarrow \infty$$

$$U(r) \rightarrow 0$$

$$r_i \rightarrow \infty$$

$$U(r_i) = 0$$

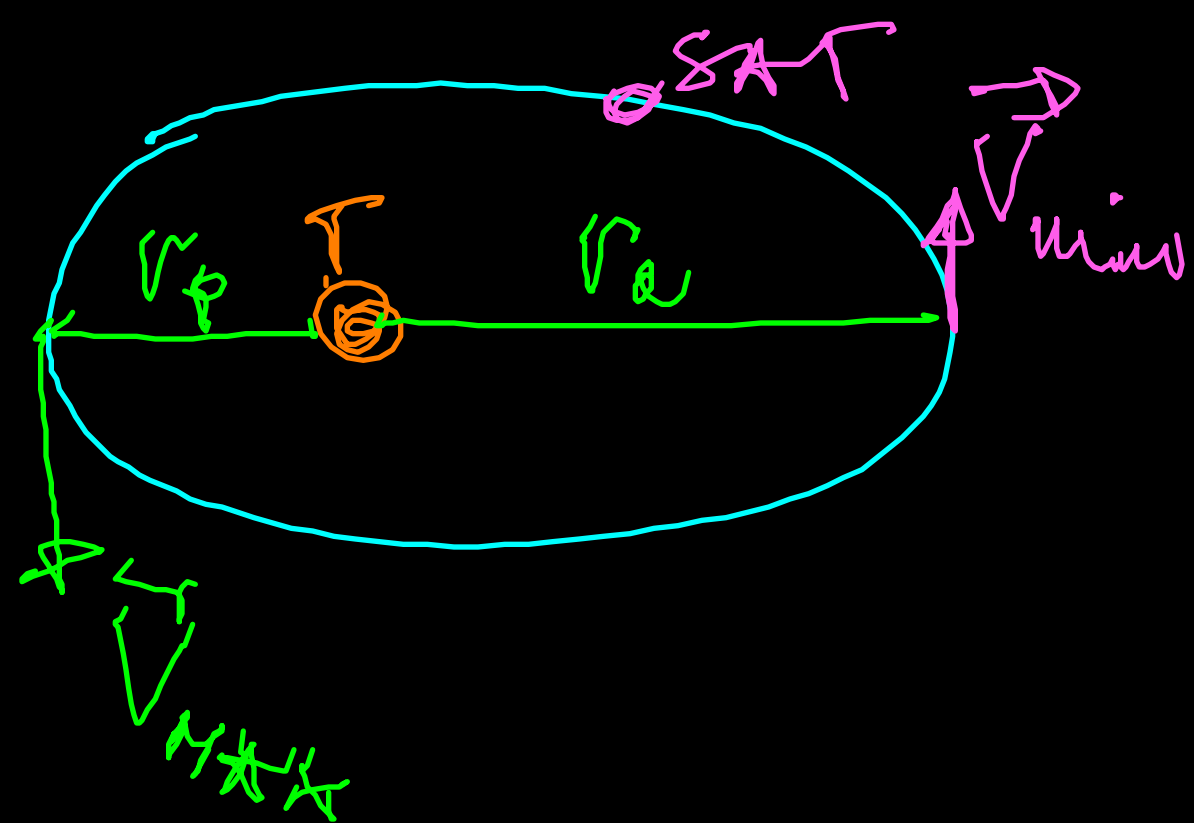




\vec{F}_G è conservativa \Rightarrow E è costante

Per il SAT. $E = \frac{1}{2} m v^2 - \frac{GM_T m_s}{r} \leftarrow U(r)$

In pratica i SAT. sono in orbite circolari con $v = \text{cost}$



$$m a_c = \frac{m v^2}{r} = F_G = \frac{GM_T m}{r^2}$$

$$K_s \approx \frac{1}{2} m v^2 = \frac{1}{2} \frac{GM_T m}{r} = \frac{1}{2} |U(r)|$$

$$E_s = \frac{1}{2} \frac{GM_T m}{r} - \frac{GM_T m}{r} = -\frac{GM_T m}{2r} < 0$$

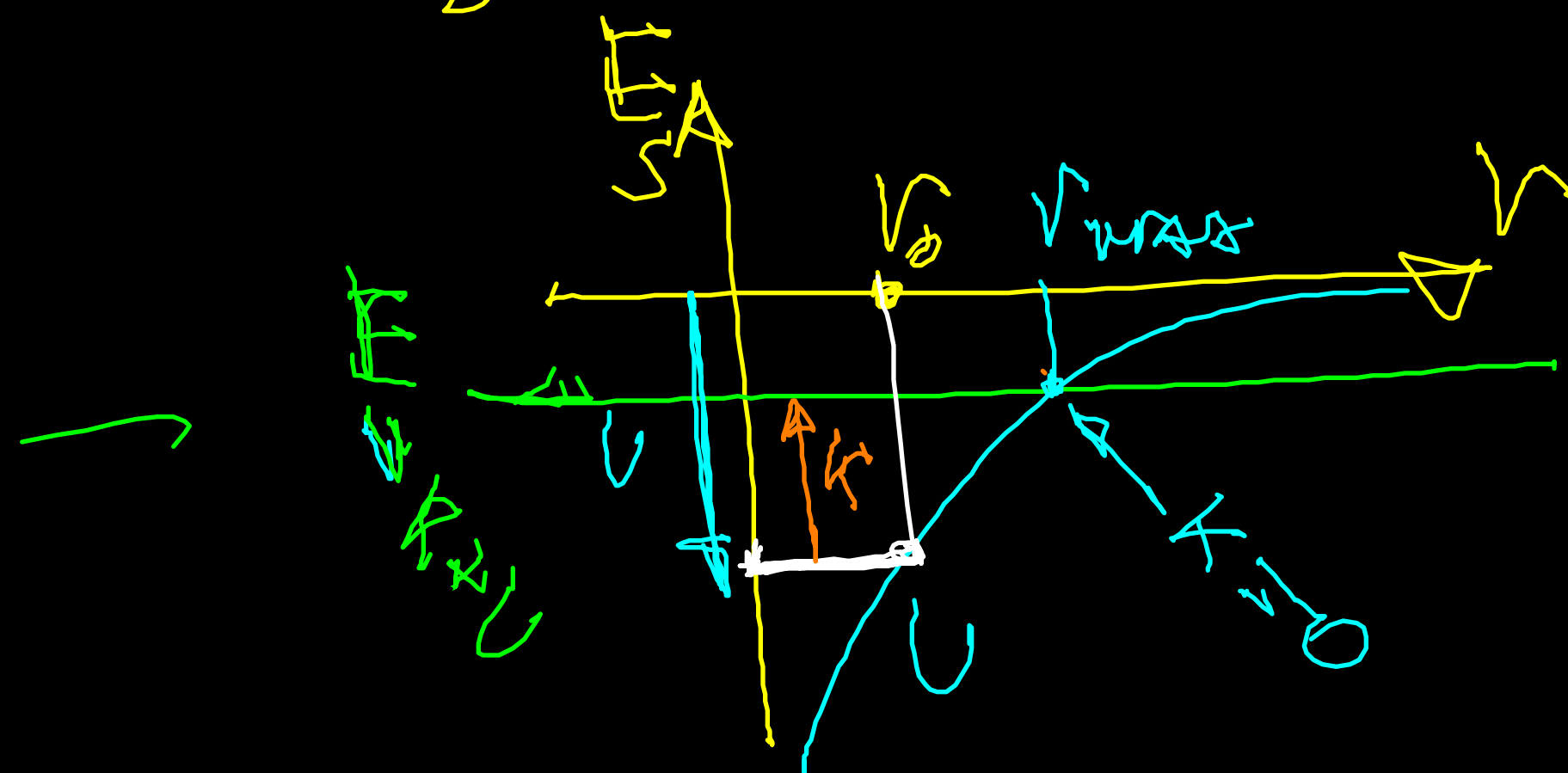
COR 1

SAT. "LIBERO" HA $U(r) \rightarrow 0$ per $r \rightarrow \infty$

$$E_{\text{lib}} \approx \frac{1}{2} \mu v^2 \geq 0 \quad \underbrace{K \geq 0 \text{ e } U \approx 0}$$

SE $E_s < 0$, per avere K almeno $= 0$
deve essere "fornita" di energia

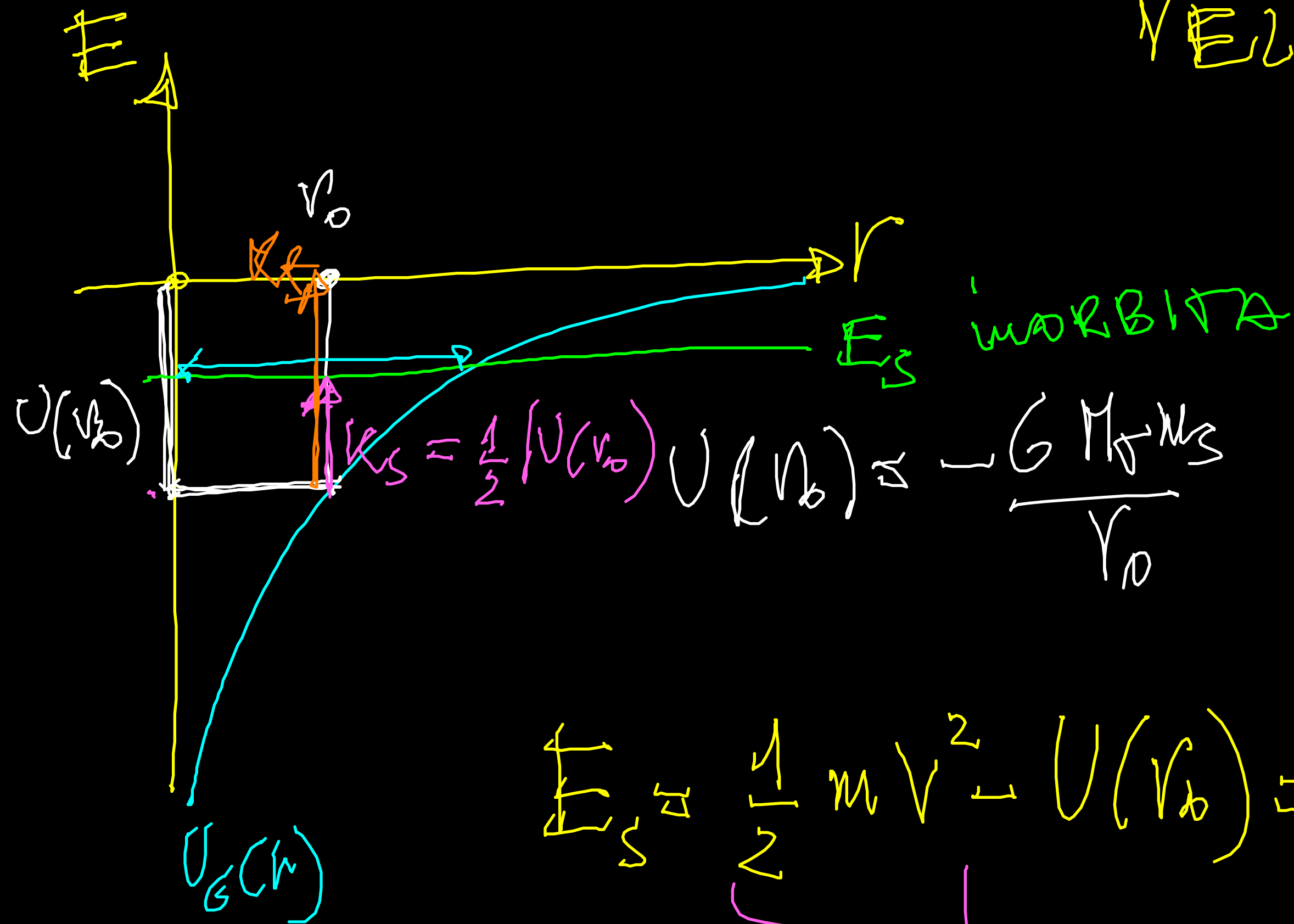
\Rightarrow Se $E_s < 0 \Rightarrow$ IL SAT. È LEGATO



VELOCITÀ DI FUGA

↳ Per sfuggire alla gravità deve partire

$E_S \rightarrow \odot$
 chiuso



$$E_S = \frac{1}{2} m v^2 - U(r_0) = -\frac{GM_T m_S}{2r_0}$$

$$E = \odot = -\frac{GM_T m_S}{r_0} + \frac{1}{2} m_S v_f^2 \Rightarrow v_f = \sqrt{2 \frac{GM_T}{r_0}}$$

$$Q_c = \frac{v^2}{r}$$

$v \neq v_f$

$$V_f = \sqrt{\frac{2GM_T}{r_0}}$$

$$r_0 = r_T = 6.4 \times 10^6 \text{ m}$$

$$M_T = 6 \times 10^{24} \text{ kg}$$

$$G = 6.67 \times 10^{-11} \frac{\text{N}}{\text{kg}^2 \text{m}^2}$$

$$V_f = \sqrt{\frac{2 \cdot (6.67 \times 10^{-11}) (6 \times 10^{24})}{6.4 \times 10^6}} \rightarrow \sqrt{12 \cdot 10^7} \frac{\text{m}}{\text{s}}$$

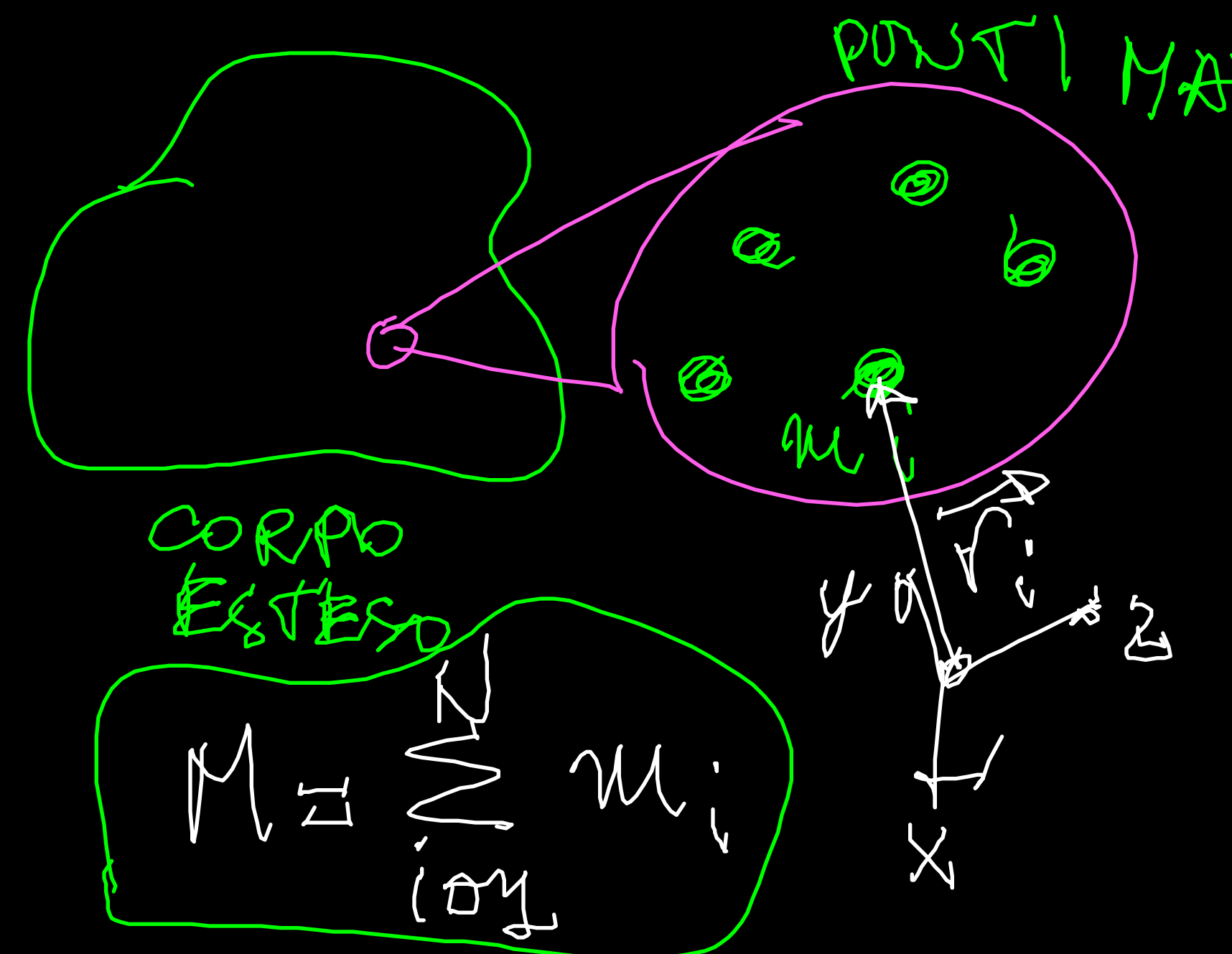
$$= \sqrt{120 \times 10^6} \frac{\text{m}}{\text{s}} = 11 \times 10^3 \frac{\text{m}}{\text{s}} = 11 \frac{\text{km}}{\text{s}}$$

$$M_{\text{BH}} \left(\frac{M_{\text{BH}}}{r_{\text{BH}}} \right)$$

$$= \frac{c^2}{2G} = 2.2 \times 10^{27} \frac{\text{kg}}{\text{m}}$$

$$\left(\frac{M_T}{r_T} \right) = \frac{6 \times 10^{24} \text{ kg}}{6.4 \times 10^6 \text{ m}} \approx 10^{18} \frac{\text{kg}}{\text{m}}$$

MOTO DEL SISTEMA (... DI PUNTI MATERIALI)



$$M = \sum_{i=1}^N m_i$$

$N \approx$ num. tot. di punti mat.
 $\approx N_A \approx 6.023 \times 10^{23}$

V punto m_i

$$\begin{bmatrix} \vec{V}_i(t) \\ \vec{V}_{oi} \end{bmatrix} \Rightarrow 6 \times N_A \text{ variabili}$$

DEVO \rightarrow IMPOSSIBILE

~~TROVARE DELLE~~
 "REGOLARITA'" E
 "PROPRIETA' MEDIE"
 PER RIDURRE LE VARIABILI

