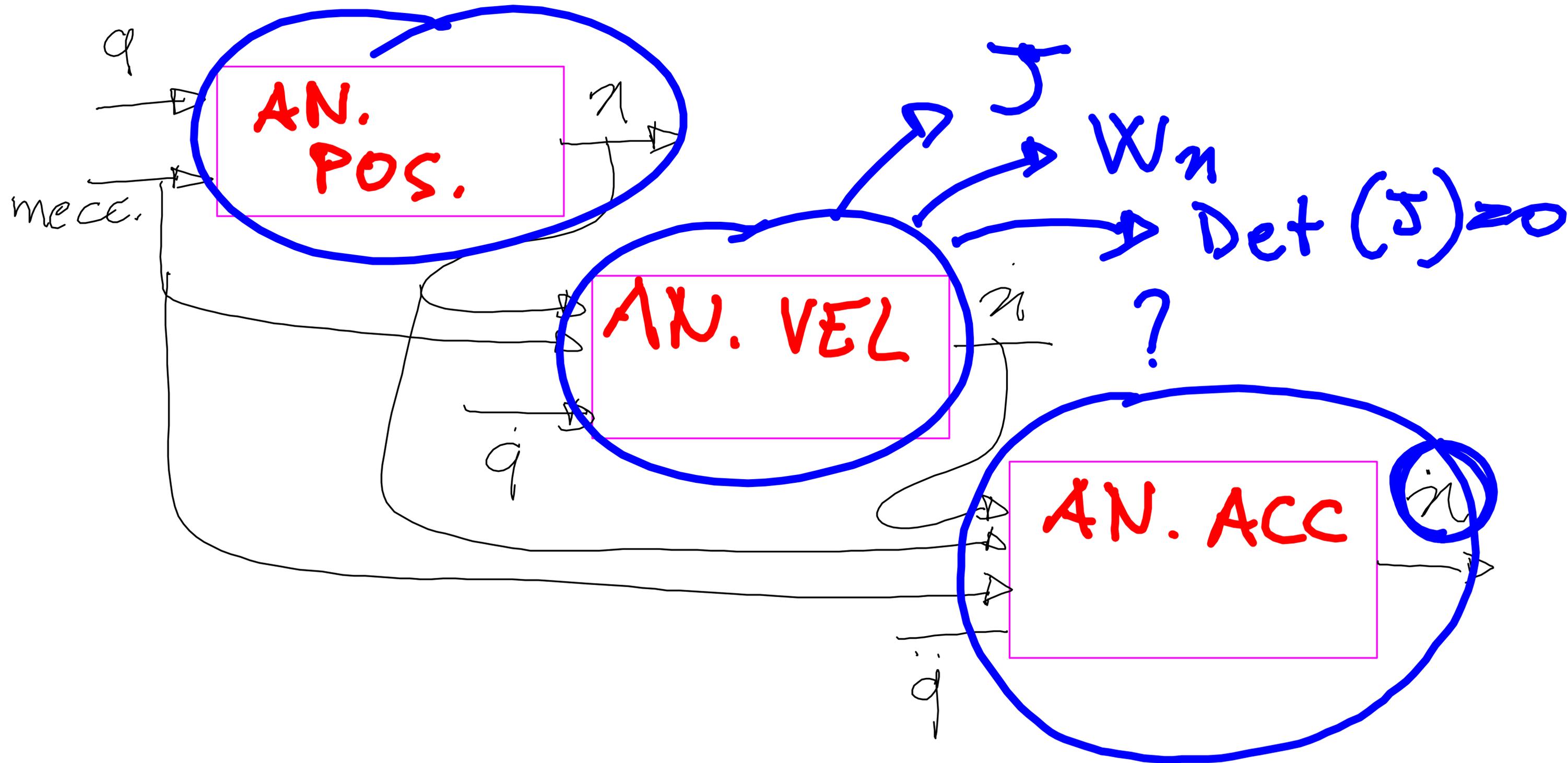


AN. ACCELERAZIONE



$$J \dot{x} + A \dot{q} = 0$$

$$\dot{J} \dot{x} + J \ddot{x} + \dot{A} \dot{q} + A \ddot{q} = 0$$

$$\Leftrightarrow \ddot{x} = - \underbrace{J^{-1}}_{\text{red}} \left(\underbrace{A \ddot{q}}_{\text{red}} + \underbrace{\dot{A} \dot{q}}_{\text{red}} + \underbrace{J \dot{x}}_{\text{red}} \right)$$

$$\ddot{x} = \cancel{B} \ddot{q}$$

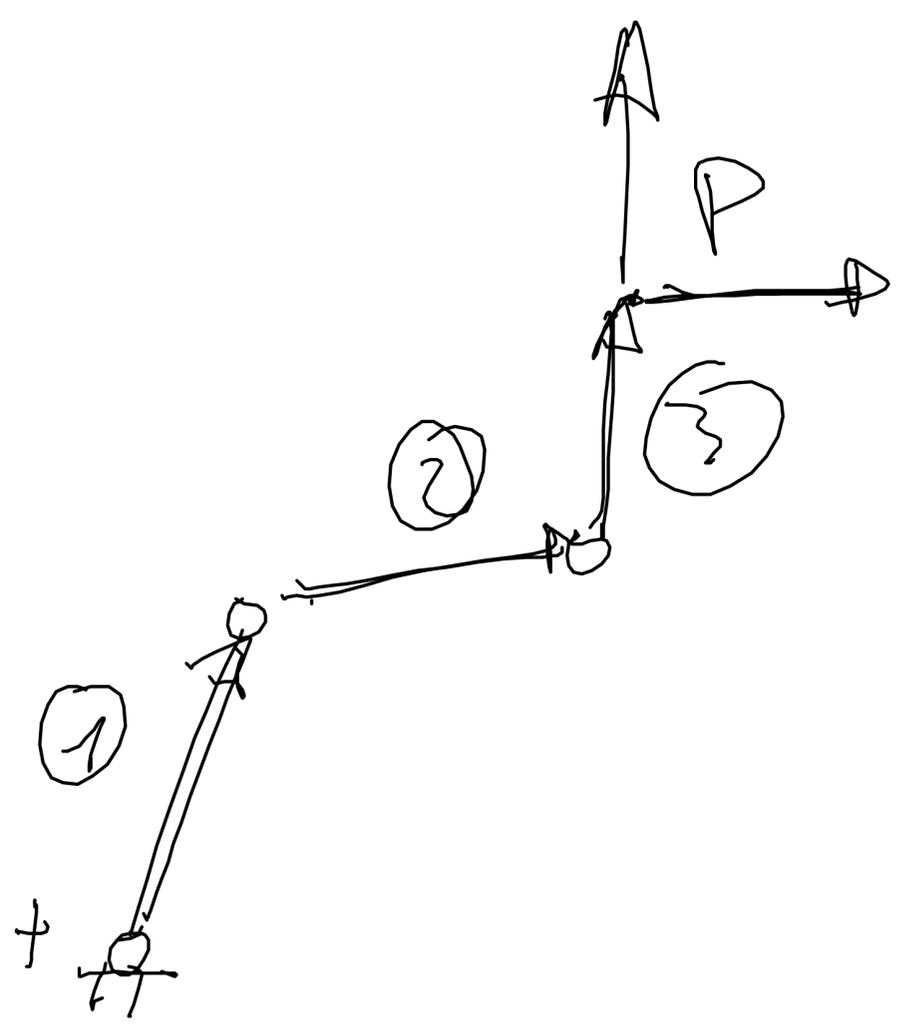
$\rightarrow \ddot{x}$

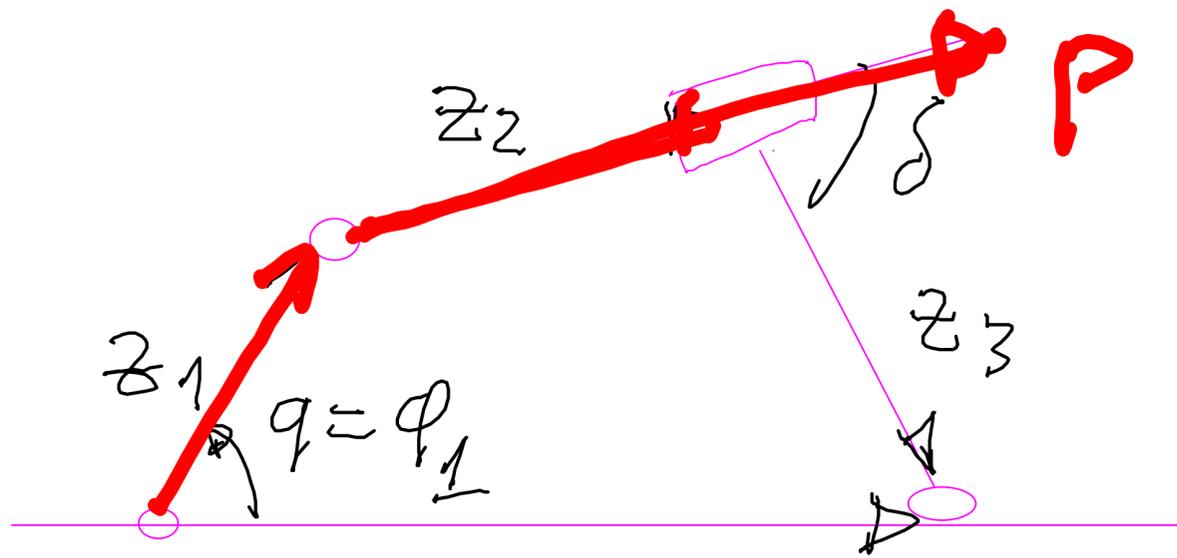
$$\sum z_i = 0$$

$$\sum \ddot{z}_i = 0 \rightarrow \ddot{z}$$

$$P = \sum_i \begin{bmatrix} c \varphi_i & -z_i s \varphi_i \\ s \varphi_i & z_i c \varphi_i \end{bmatrix} \begin{Bmatrix} \dot{z}_i \\ \dot{\varphi}_i \end{Bmatrix}$$

$$\dot{P} = \sum_i \begin{bmatrix} -s \varphi_i \dot{\varphi}_i & -\dot{z}_i s \varphi_i - z_i c \varphi_i \dot{\varphi}_i \\ c \varphi_i \dot{\varphi}_i & \dot{z}_i c \varphi_i - z_i s \varphi_i \dot{\varphi}_i \end{bmatrix} \begin{Bmatrix} \dot{z}_i \\ \dot{\varphi}_i \end{Bmatrix} + \begin{bmatrix} c \varphi_i & -z_i s \varphi_i \\ s \varphi_i & z_i c \varphi_i \end{bmatrix} \begin{Bmatrix} \ddot{z}_i \\ \ddot{\varphi}_i \end{Bmatrix}$$





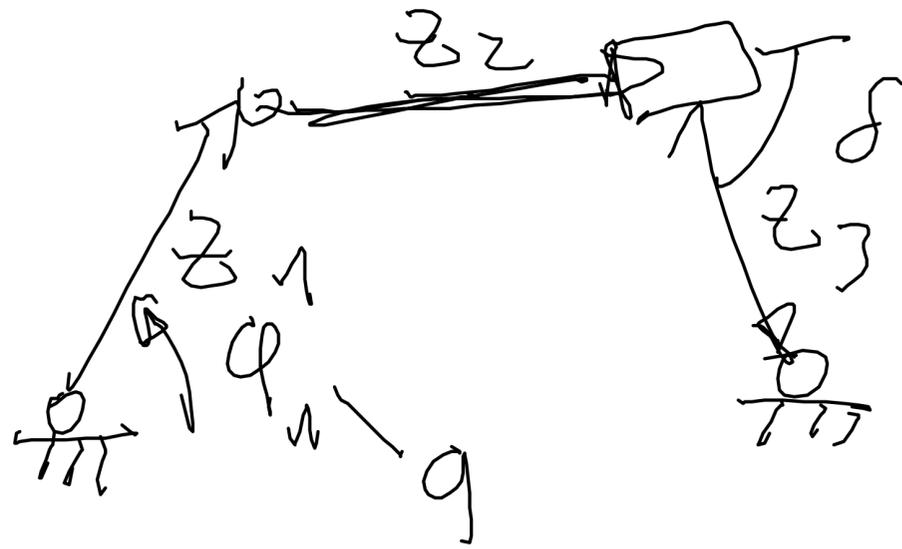
$$J = \begin{bmatrix} -z_2 s \phi_2 - z_3 s(\phi_2 - \delta) & c \phi_2 \\ z_2 c \phi_2 + z_3 c(\phi_2 - \delta) & s \phi_2 \end{bmatrix}$$

$$j = \begin{bmatrix} -\dot{\delta}_2 s \phi_2 - z_2 c \phi_2 \dot{\phi}_2 - z_3 c(\phi_2 - \delta) \dot{\phi}_2 & -s \phi_2 \dot{\phi}_2 \\ \dot{z}_2 c \phi_2 - z_2 s \phi_2 \dot{\phi}_2 - z_3 s(\phi_2 - \delta) \dot{\phi}_2 & c \phi_2 \dot{\phi}_2 \end{bmatrix}$$

$$\dot{A} = \begin{bmatrix} -z_1 c \phi_1 \\ -z_1 s \phi_1 \end{bmatrix} \dot{\phi}_1$$

$$A = \begin{bmatrix} -z_1 s \phi_1 \\ z_1 c \phi_1 \end{bmatrix}$$

$$J = J(q)$$



$$J \begin{Bmatrix} \dot{\varphi}_2 \\ \dot{z}_2 \end{Bmatrix} + A \dot{\varphi}_1 = 0$$

$$\begin{bmatrix} -\underline{z}_2 \delta \underline{\varphi}_2 - \underline{z}_3 \delta (\underline{\varphi}_2 - \delta) & \underline{c} \underline{\varphi}_2 \\ \underline{z}_2 \underline{c} \underline{\varphi}_2 + \underline{z}_3 \underline{c} (\underline{\varphi}_2 - \delta) & \delta \underline{\varphi}_2 \end{bmatrix}$$

$$J = J(z_2(q), \varphi_2(q))$$