

$$\begin{cases} \dot{\varphi}_2 \\ \dot{\varphi}_3 \end{cases}$$

$$\begin{cases} z_1 c q + \underline{z_2 c \varphi_2} + \underline{z_3 c \varphi_3} + \overbrace{z_4 c \varphi_4}^{-z_4} = 0 \\ z_1 s q + \underline{z_2 s \varphi_2} + \underline{z_3 s \varphi_3} = 0 \end{cases}$$

$$J = \begin{bmatrix} -z_2 s \varphi_2 & -z_3 s \varphi_3 \\ z_2 c \varphi_2 & z_3 c \varphi_3 \end{bmatrix}$$

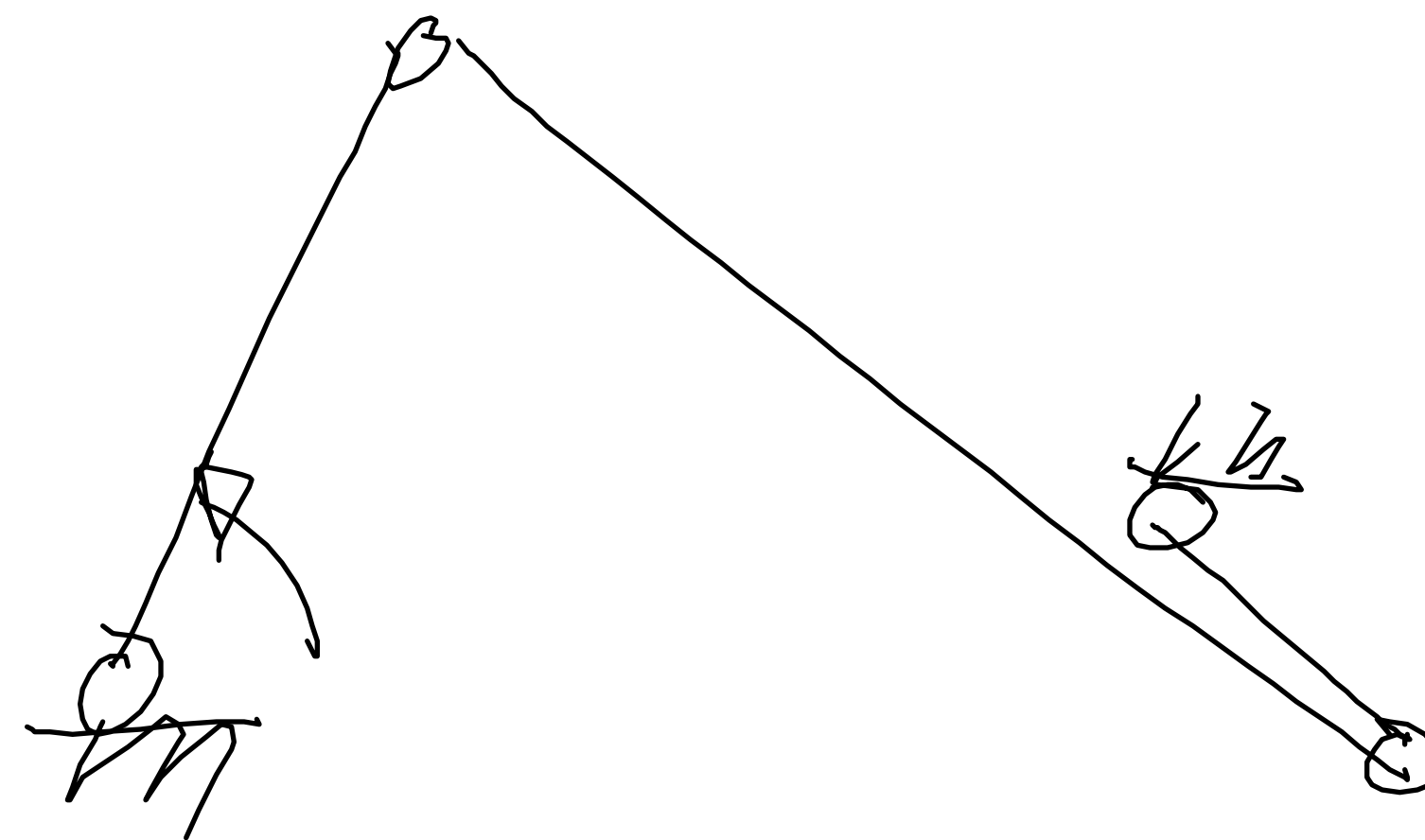
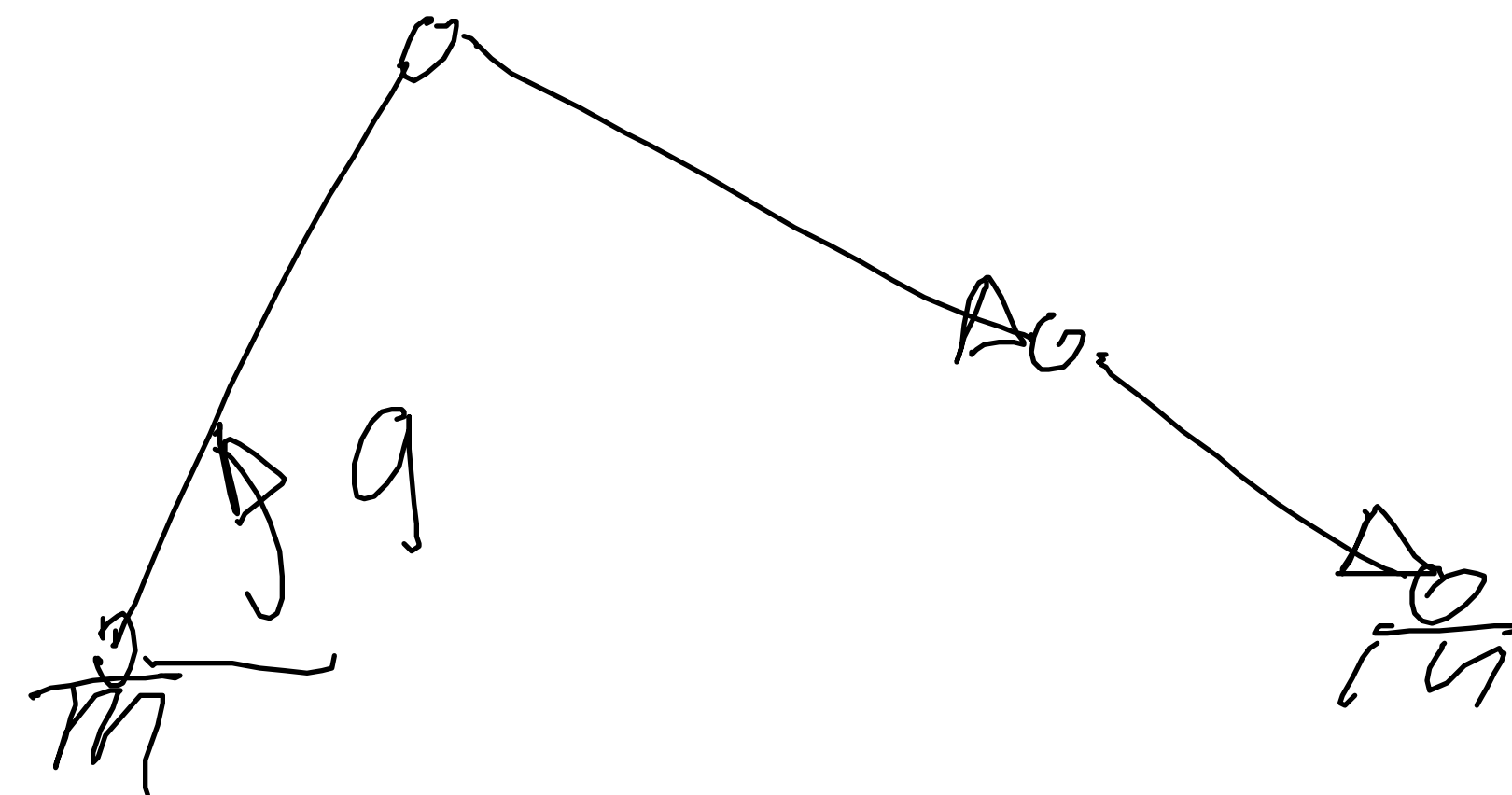
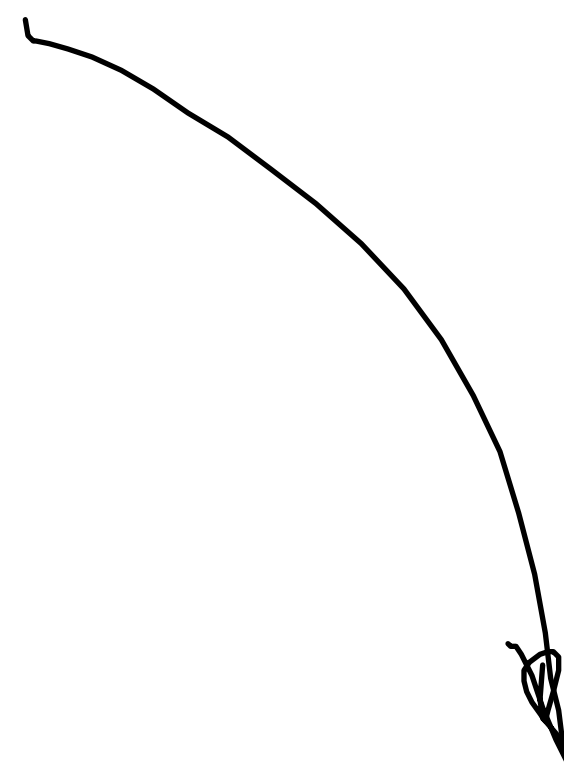
$$\det(J) = 0 \Rightarrow$$

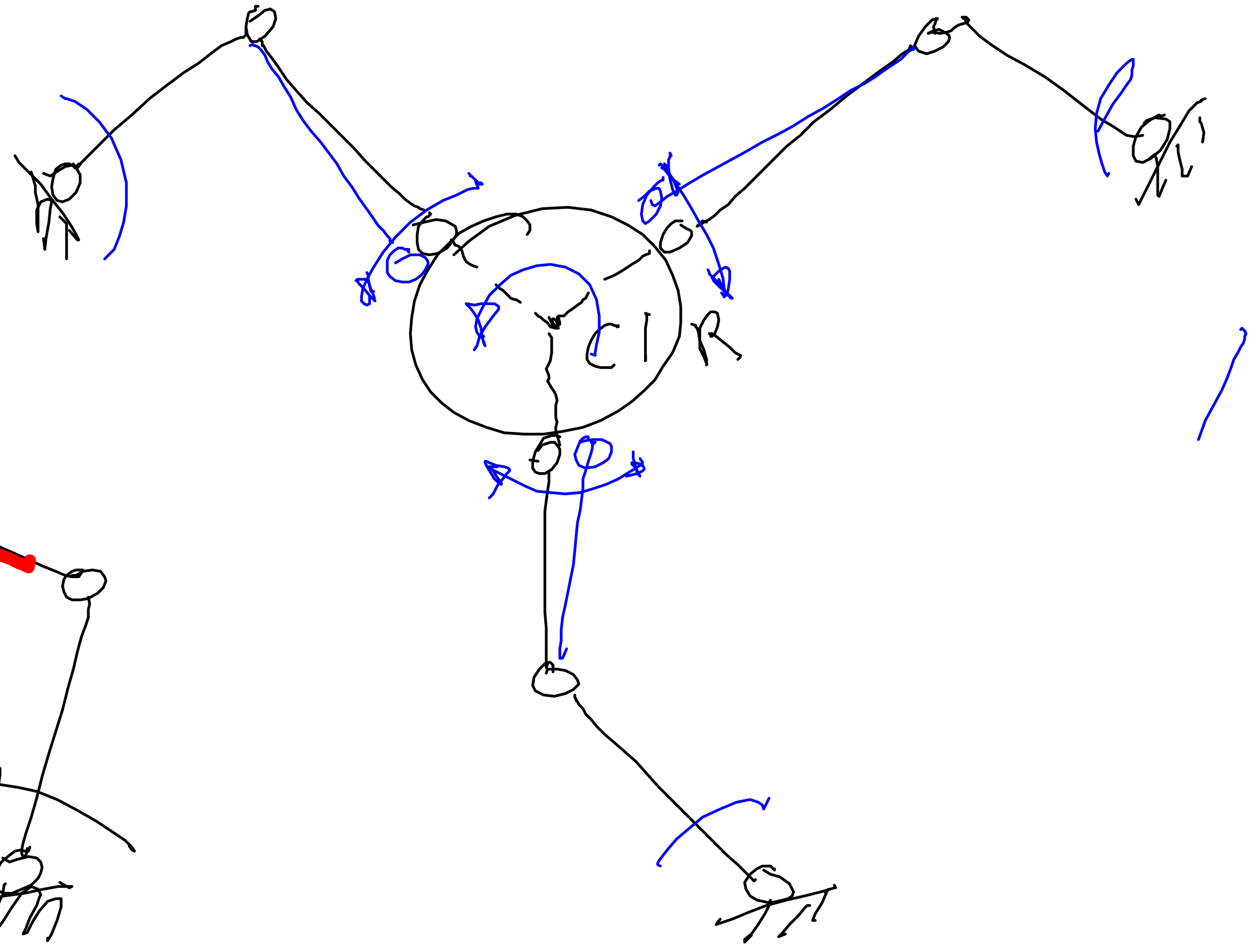
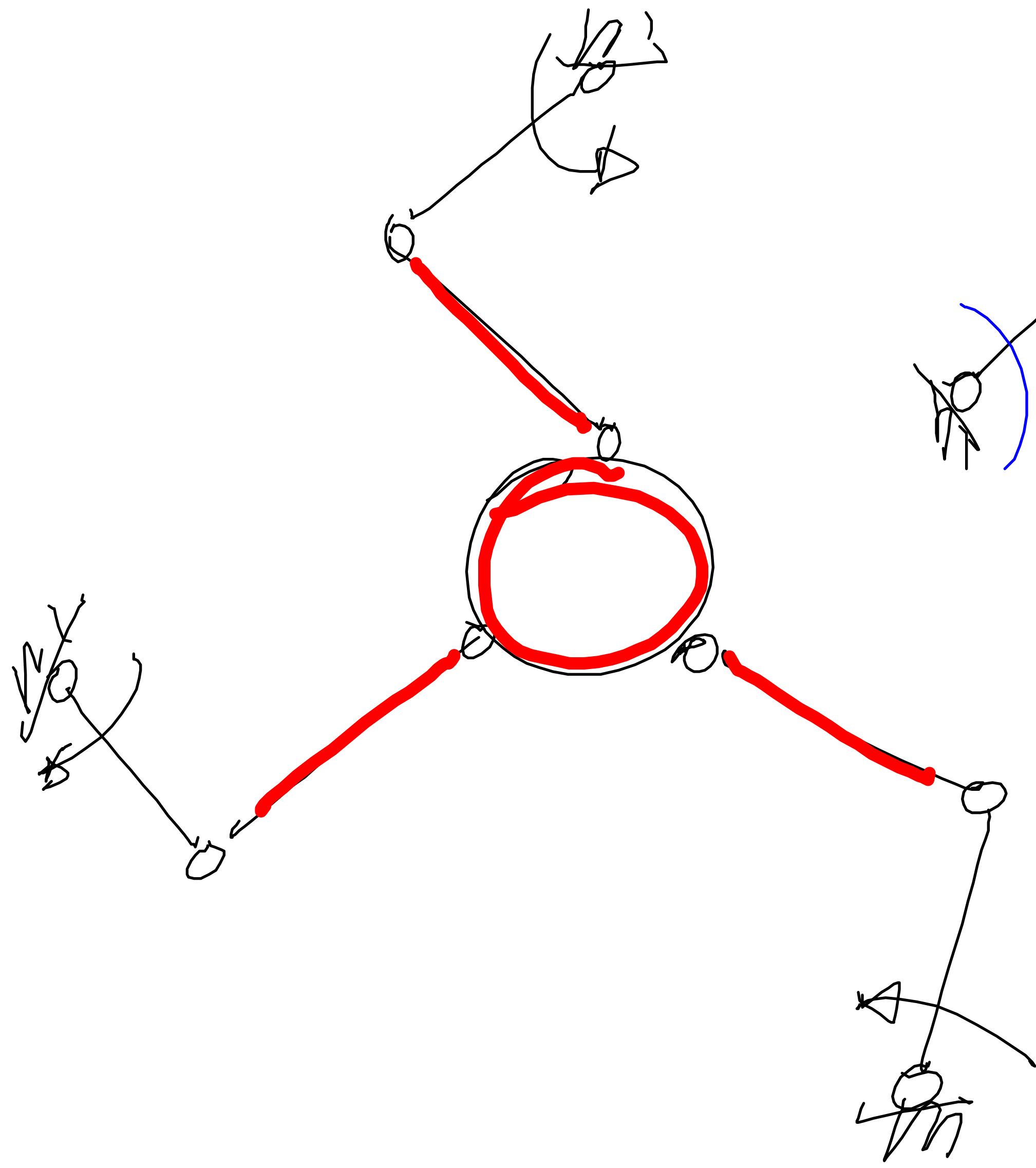
$$-s \varphi_2 c \varphi_3 + c \varphi_2 s \varphi_3 = 0$$

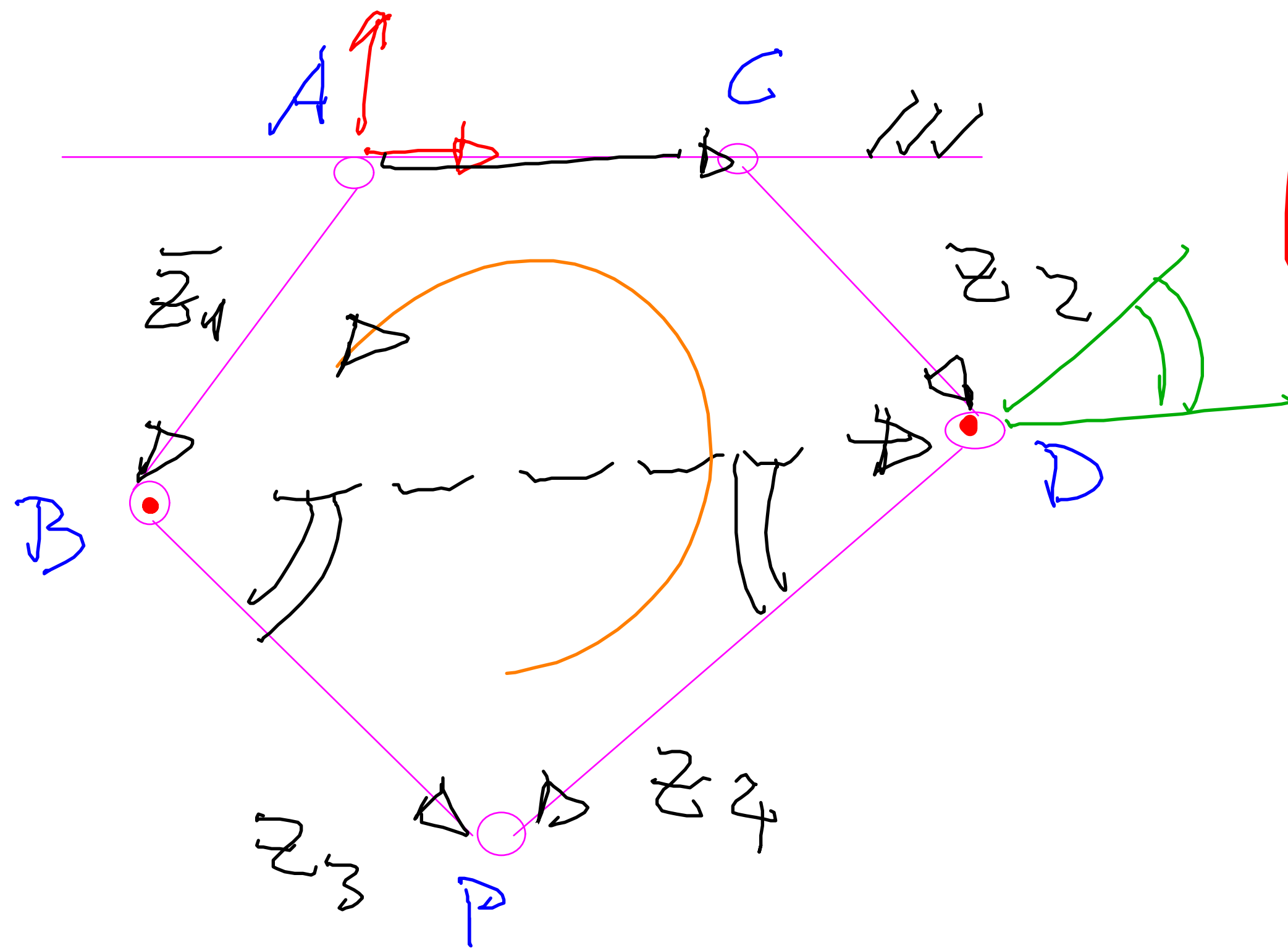
$$s(\varphi_3 - \varphi_2) = 0$$

$$\varphi_3 = \varphi_2$$

$$\varphi_3 = \varphi_2 + \overline{11}$$







$$q_1 = -134^\circ$$

$$q_2 = -55^\circ$$

$$W_n$$

$$W_n z = -J^{-1} A$$


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$$w_{ij}$$

An. cinem.  $\rightarrow$   $B = z_1 \begin{cases} c q_1 \\ s q_1 \end{cases}$   $D = \begin{cases} AC \\ 0 \end{cases} + z_2 \begin{cases} c q_2 \\ s q_2 \end{cases}$

$$\varphi_{BD} = \arctan 2(y_D - y_B, x_D - x_B)$$

$$BD = \|D - B\|$$

$$\hat{D} \hat{B} P = \hat{B} \hat{D} P = \alpha \cos \left( \frac{BD^2 + z_3^2 - z_4^2}{2BD z_3} \right)$$

$$\phi_3 = \phi_{BD} - D \hat{B} P$$

$$\phi_4 = \phi_{BD} + D \hat{B} P + \pi$$

AN. VEL

$$\underline{z}_1 + \underline{z}_3 - \underline{z}_4 - \underline{z}_2 - \bar{A}C = 0$$

$$\begin{matrix} \textcircled{J} \\ \textcircled{A} \end{matrix} \begin{matrix} \dot{\phi}_3 \\ \dot{\phi}_4 \end{matrix} + \begin{matrix} \dot{q}_1 \\ \dot{q}_2 \end{matrix} = 0$$

$$J^c = \begin{bmatrix} \underline{z}_3 s \phi_3 & \underline{z}_4 s \phi_4 \\ \underline{z}_3 c \phi_3 & -\underline{z}_4 c \phi_4 \end{bmatrix}$$

$$A = \begin{bmatrix} -\underline{z}_1 s q_1 & \underline{z}_2 s q_2 \\ \underline{z}_1 c q_1 & -\underline{z}_2 c q_2 \end{bmatrix}$$

$$\begin{matrix} \dot{\phi}_3 \\ \dot{\phi}_4 \end{matrix}$$

$$\begin{matrix} \dot{q}_1 \\ \dot{q}_2 \end{matrix}$$

$$W_n = -\underline{J}^{-1} \underline{A} = \begin{bmatrix} -0,2 & 0,92 \\ 0,91 & -0,25 \end{bmatrix}$$

$$W_n = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$a = a(q)$$

$$b = b(q)$$

$$\dots$$

$$a = a(q, \cancel{q})$$

$$\begin{cases} \dot{q}_1 = 1 \\ \dot{q}_2 = 0 \end{cases}$$

$$\begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{cases} 1 \\ 0 \end{cases} \Rightarrow \begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{cases} a \\ c \end{cases}$$

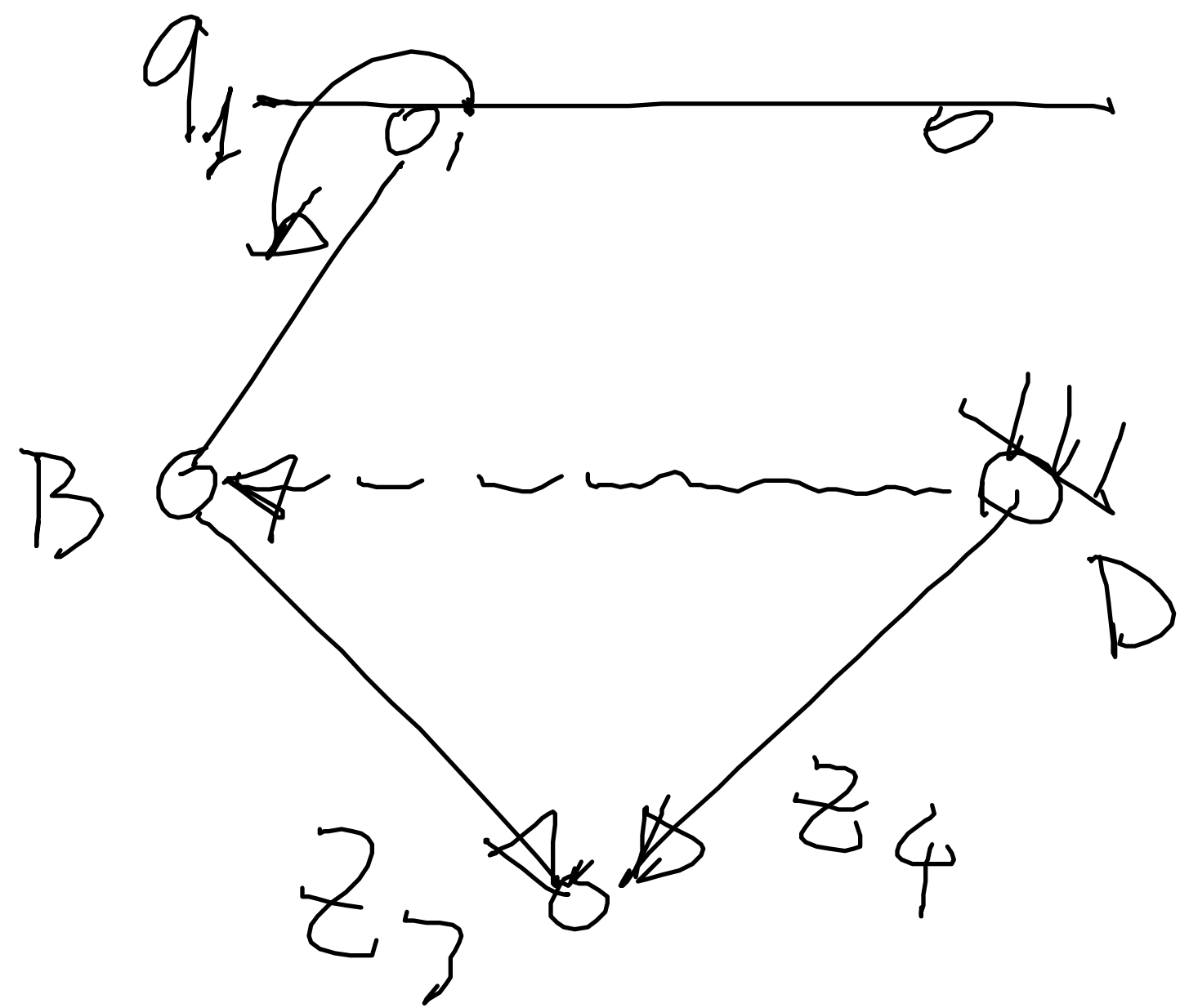
$$\begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{cases} a \\ c \end{cases}$$

$$\begin{cases} \dot{q}_1 = 0 \\ \dot{q}_2 = 1 \end{cases}$$

$$\begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{cases} 0 \\ 1 \end{cases} \Rightarrow \begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{cases} b \\ d \end{cases}$$

$$\begin{cases} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{cases} = \begin{cases} b \\ d \end{cases}$$

$$\begin{cases} \dot{q}_1 \\ \dot{q}_2 \end{cases} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



$$\bar{z}_3 - \bar{z}_4 + \bar{D}B = 0$$

$$\begin{bmatrix} -z_3 s \varphi_3 & z_4 s \varphi_4 \\ z_3 c \varphi_3 & -z_4 c \varphi_4 \end{bmatrix} \begin{Bmatrix} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{Bmatrix} = -\frac{d(\bar{D}B)}{dt}$$

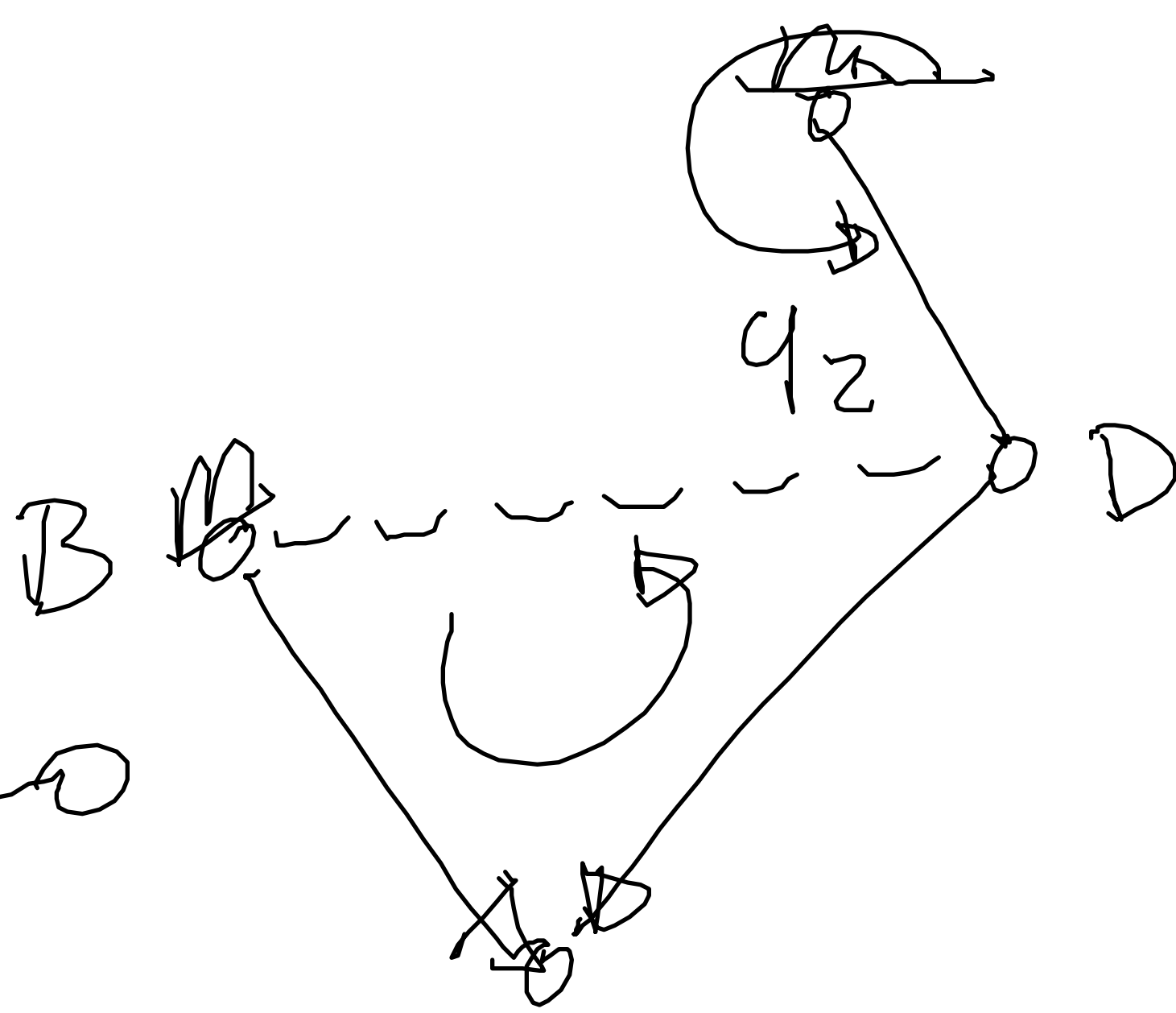
$$= -\frac{d}{dt} (\bar{B} - \bar{D})$$

$$= \begin{pmatrix} -z_3 \\ -z_4 \end{pmatrix} \begin{pmatrix} -s q_1 \\ c q_1 \end{pmatrix} \dot{q}_1$$

$$\begin{Bmatrix} \dot{\varphi}_3 \\ \dot{\varphi}_4 \end{Bmatrix} = \begin{pmatrix} -0.2 \\ 0.91 \end{pmatrix}$$

1

$$\begin{cases} \dot{q}_1 = 0 \\ \dot{q}_2 = 1 \end{cases}$$



$$z_3 - z_4 + DB = 0$$

$$\begin{cases} \dot{\phi}_3 \\ \dot{\phi}_4 \end{cases} = \begin{pmatrix} 0,92 \\ -0,25 \end{pmatrix}$$