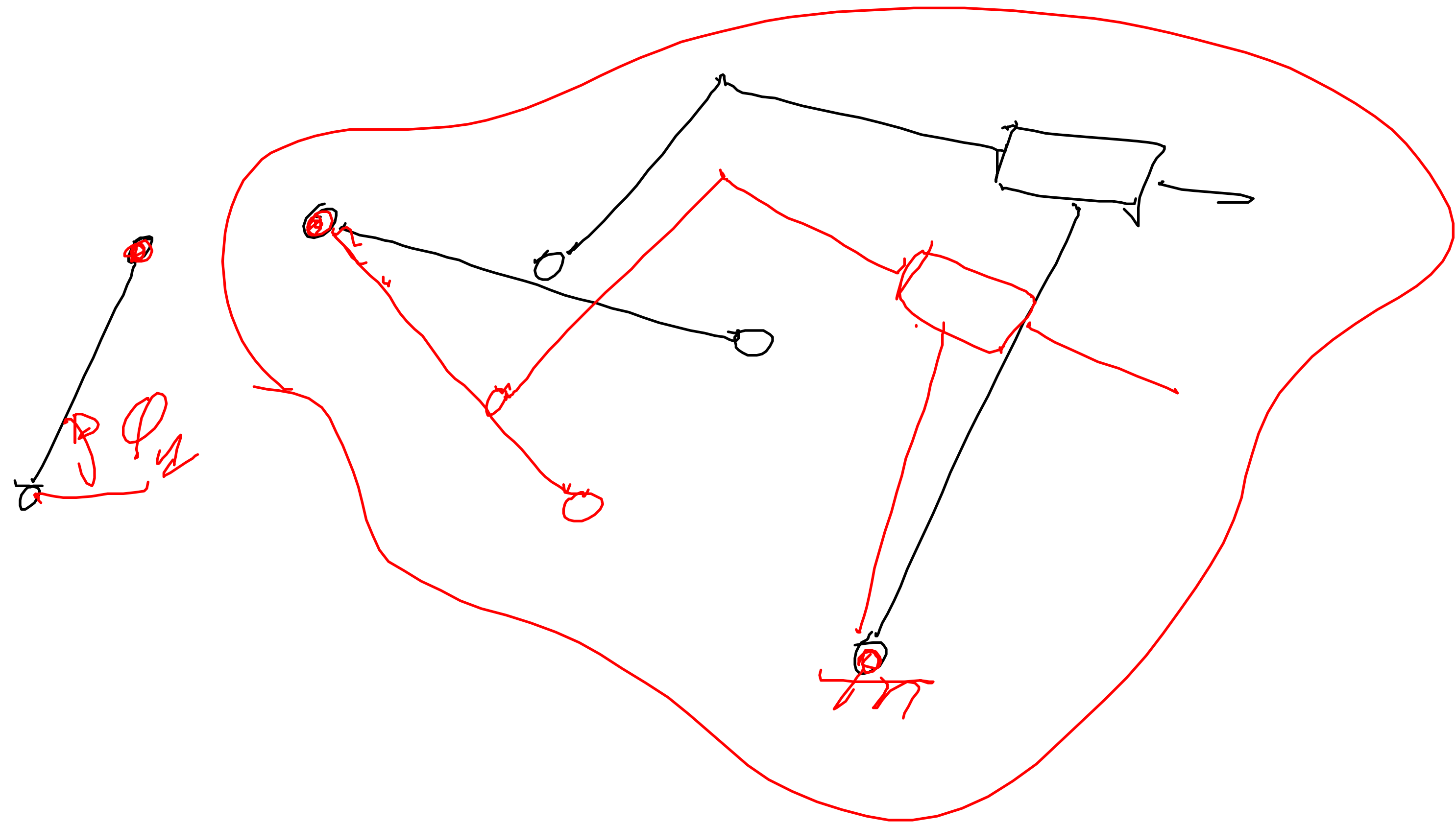
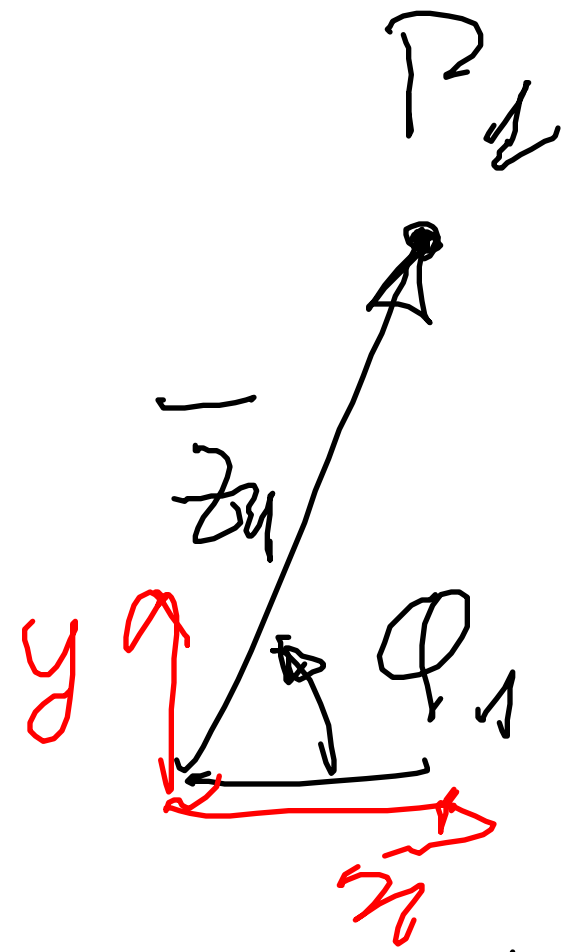
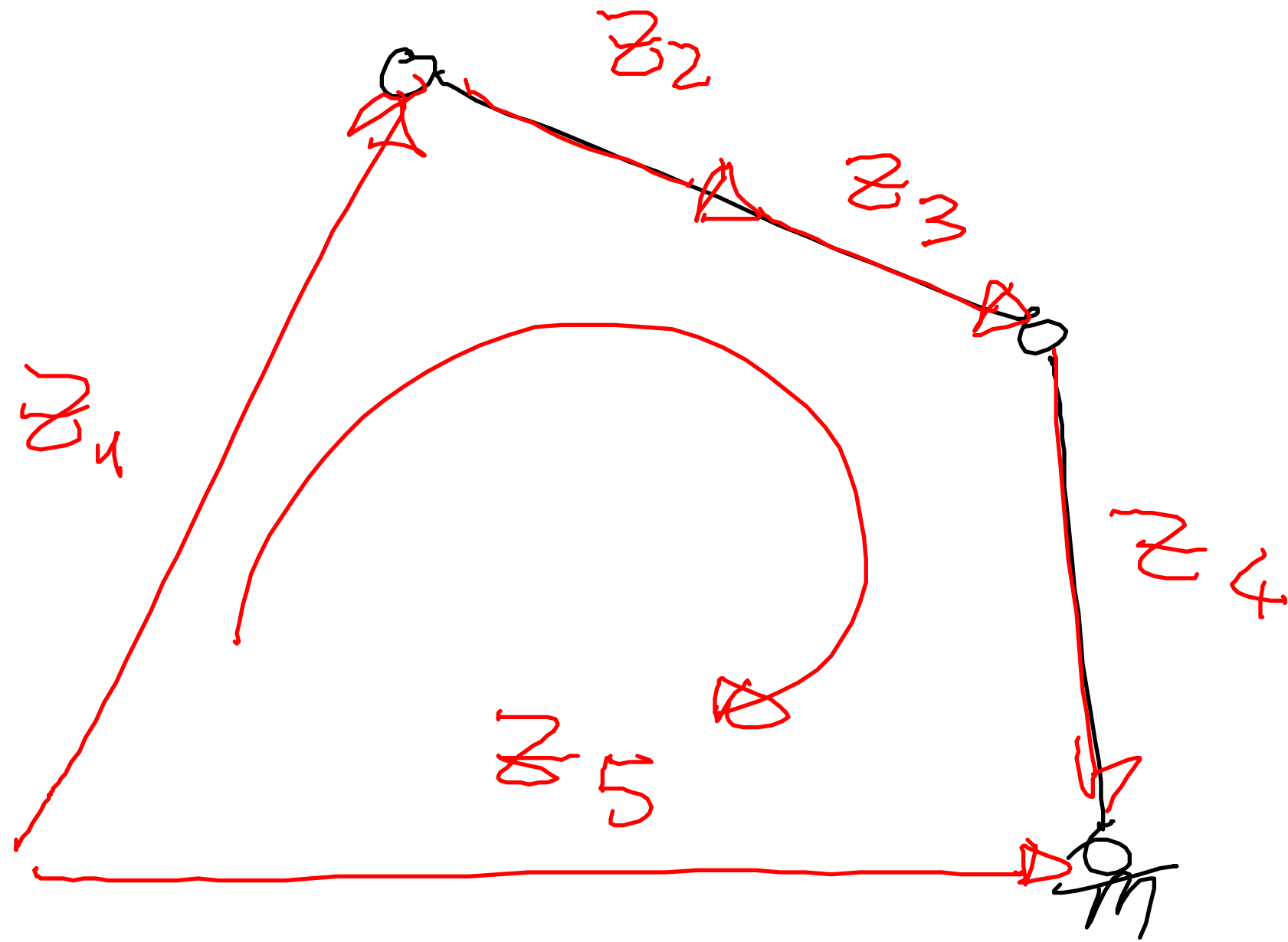


MOBILITÄ
NULLA

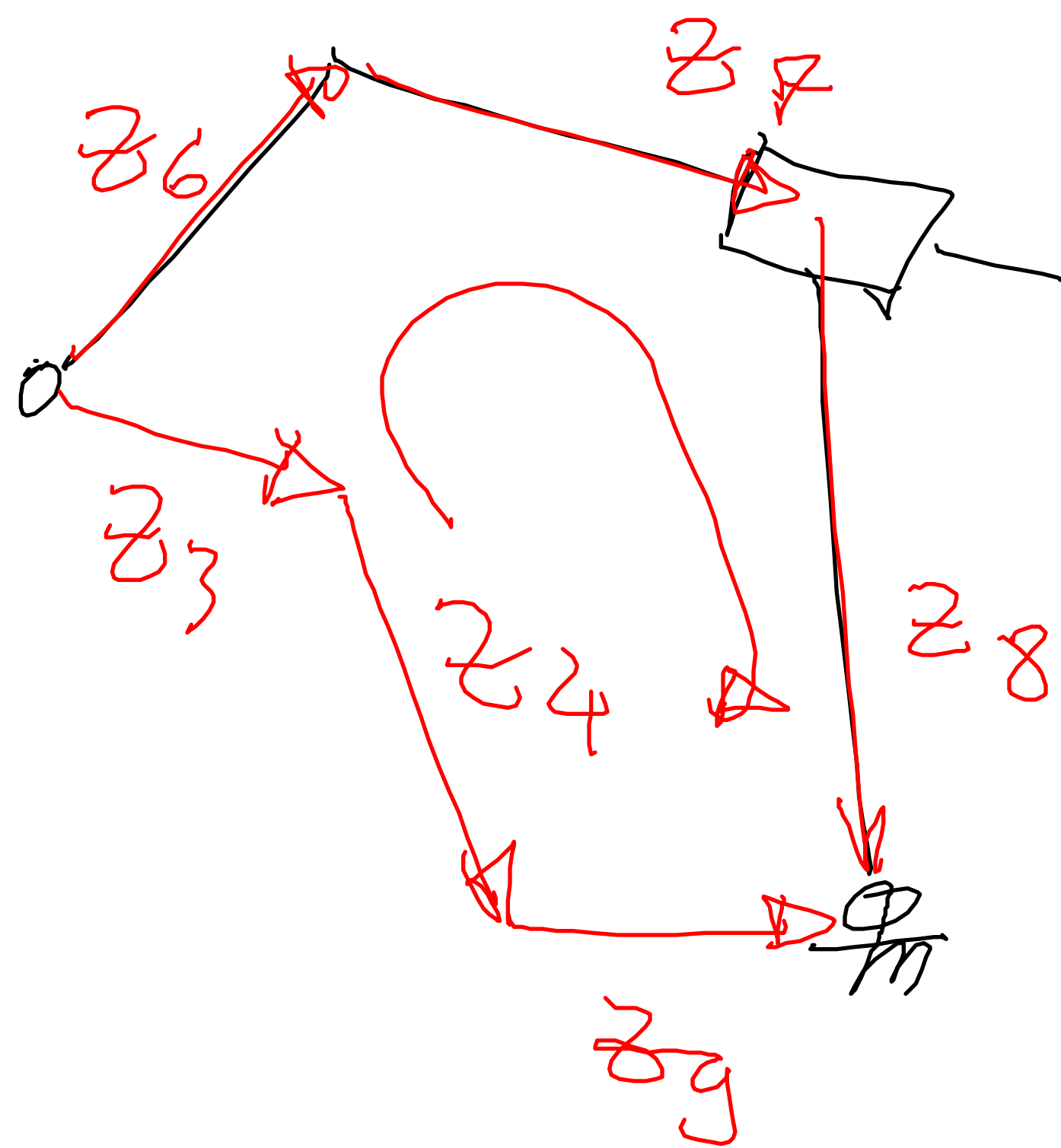




$$P_1 = z_1 \begin{cases} \cos \phi_1 \\ \sin \phi_1 \end{cases}$$



ϕ_2, ϕ_4



Φ_6, Z_7

ASSUR
DIADI

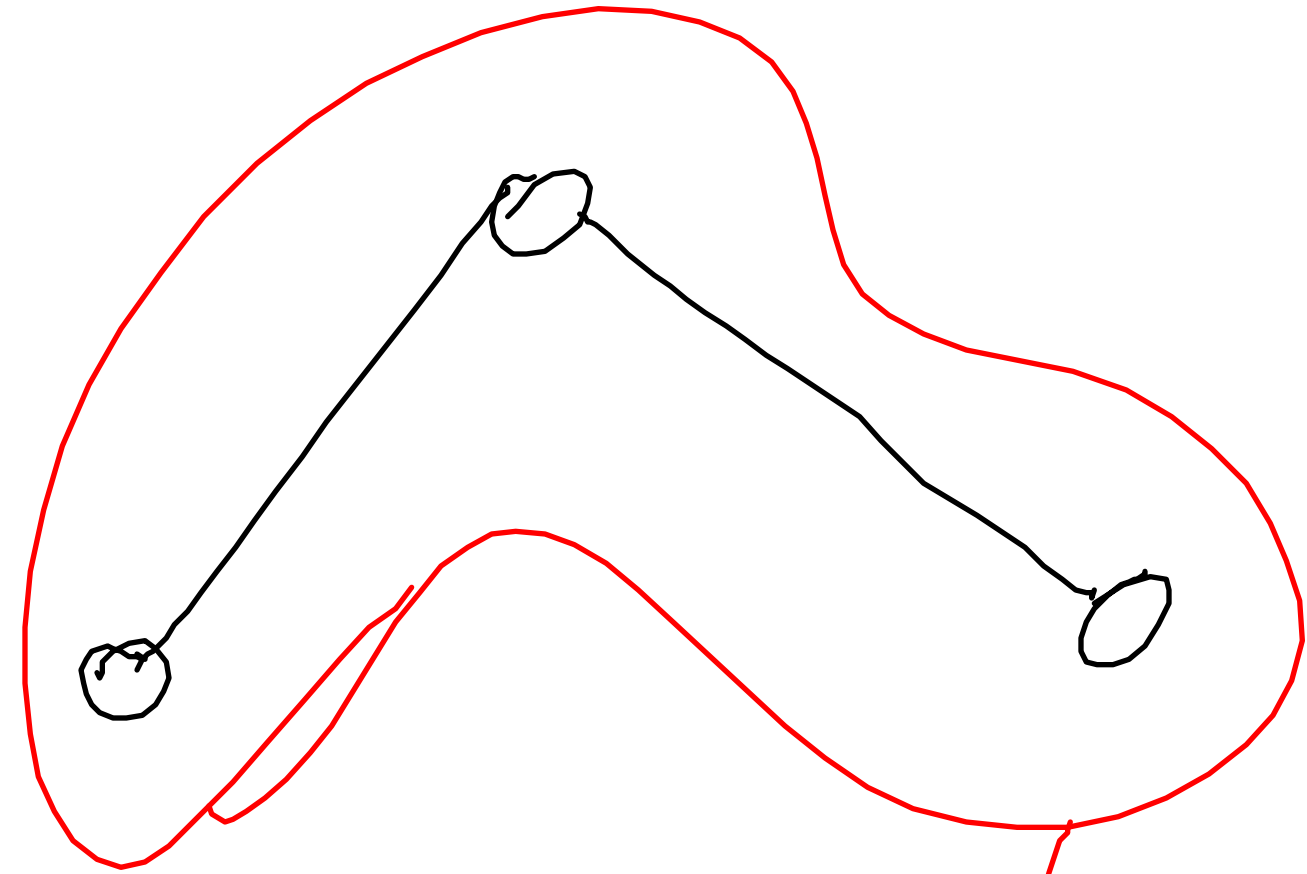
$$3(m-1) - 2 \cdot c = 0$$

$$m=3 \Rightarrow c=3$$

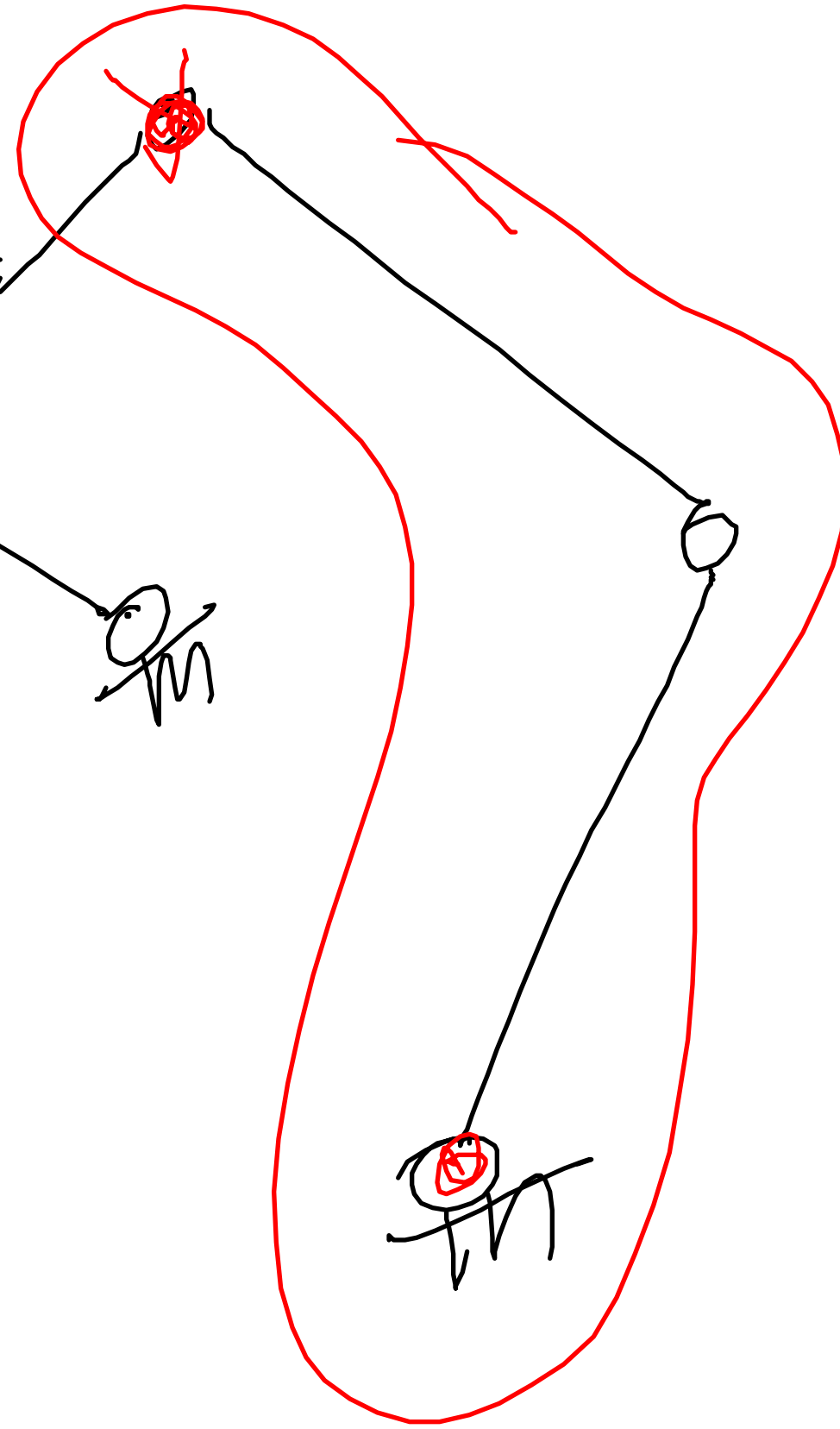
$m=4 \longrightarrow$ no sottomeccanismi

$$m=5 \Rightarrow c=6 \quad \text{TRIADI}$$

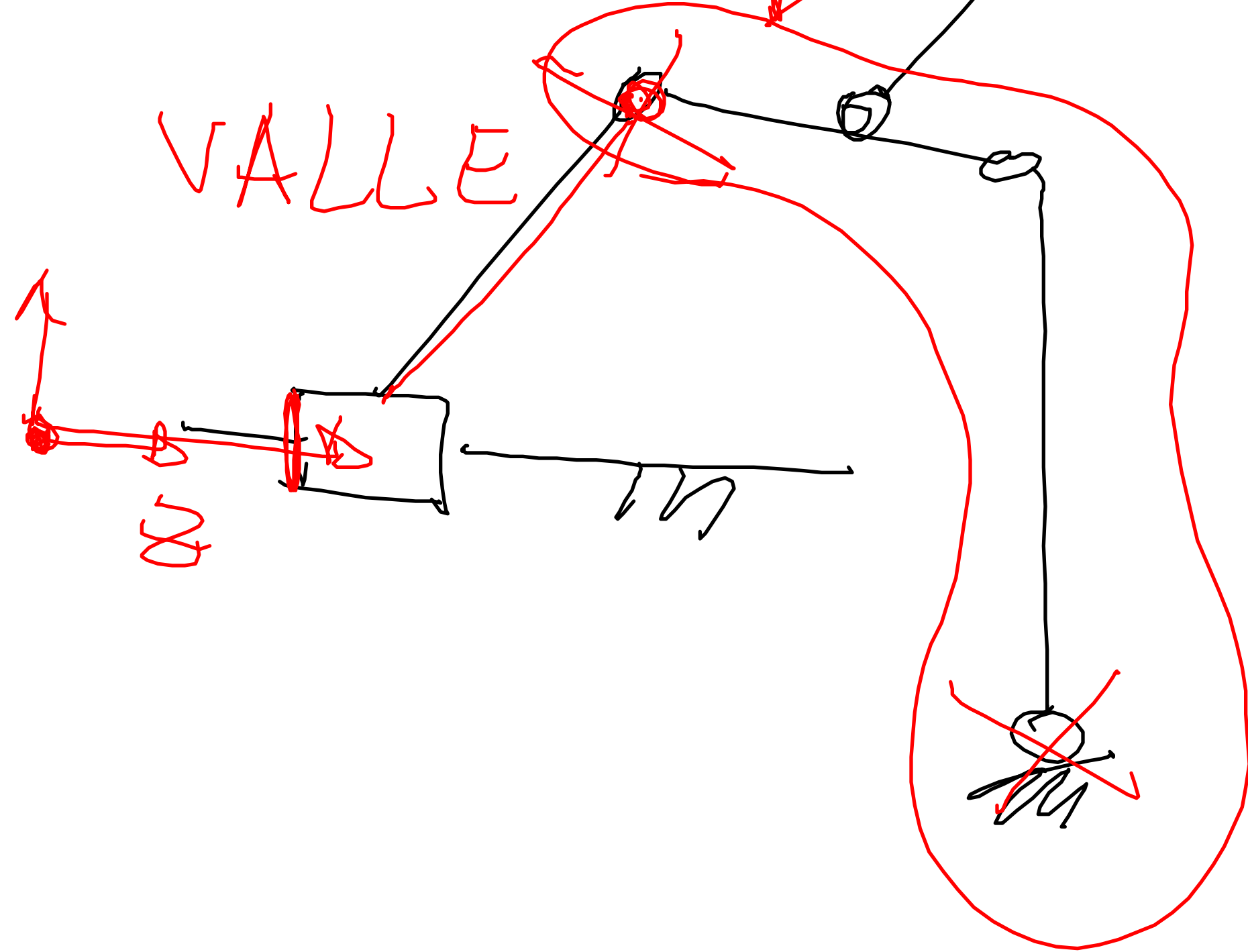
DIAD E



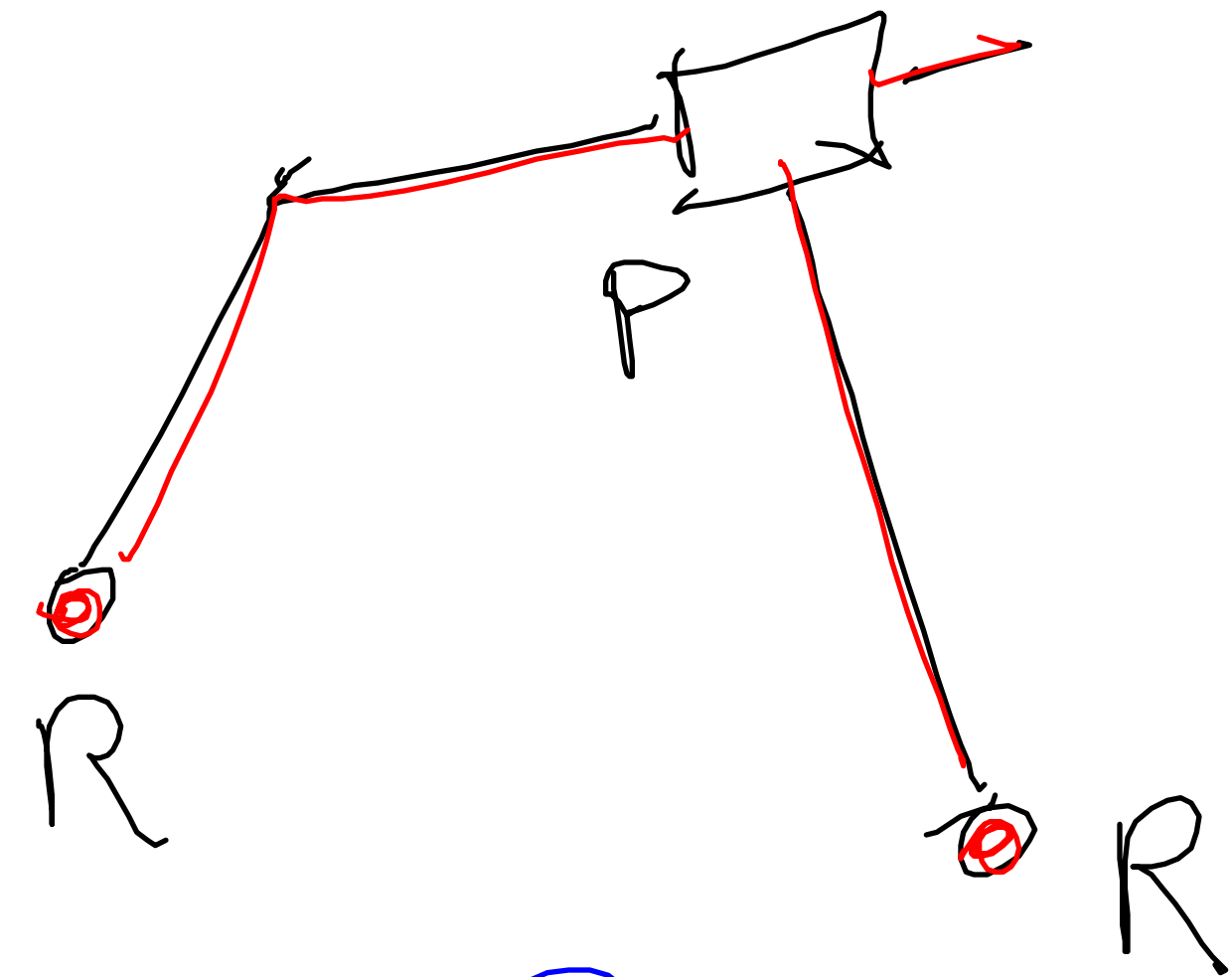
RRR



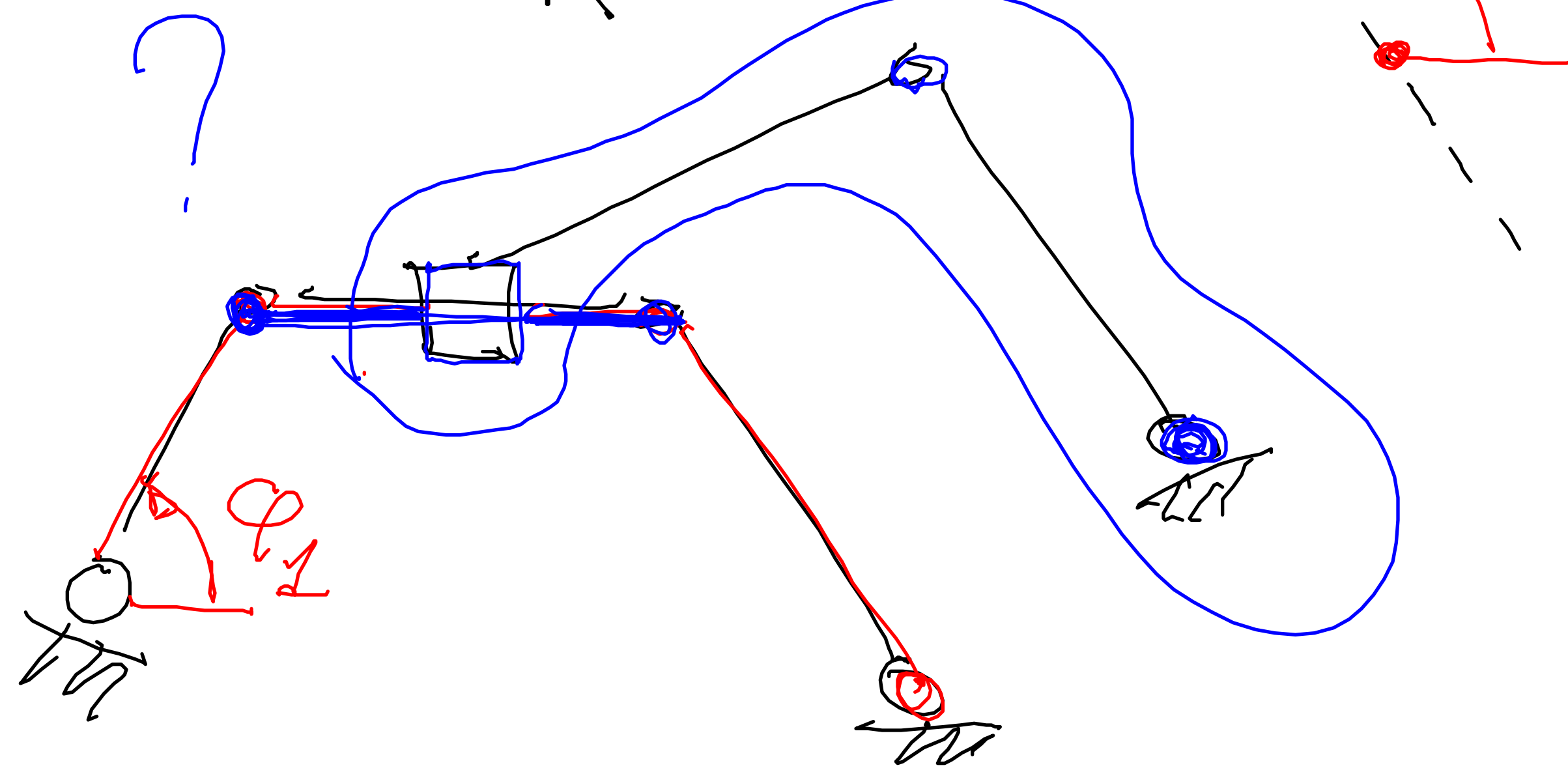
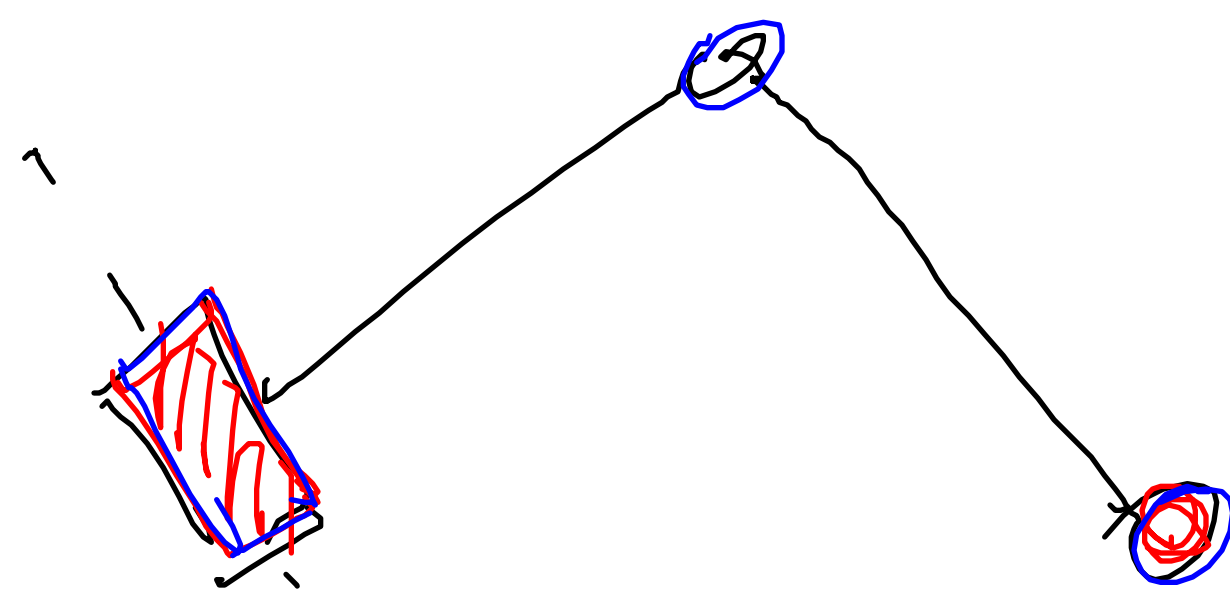
VALLE



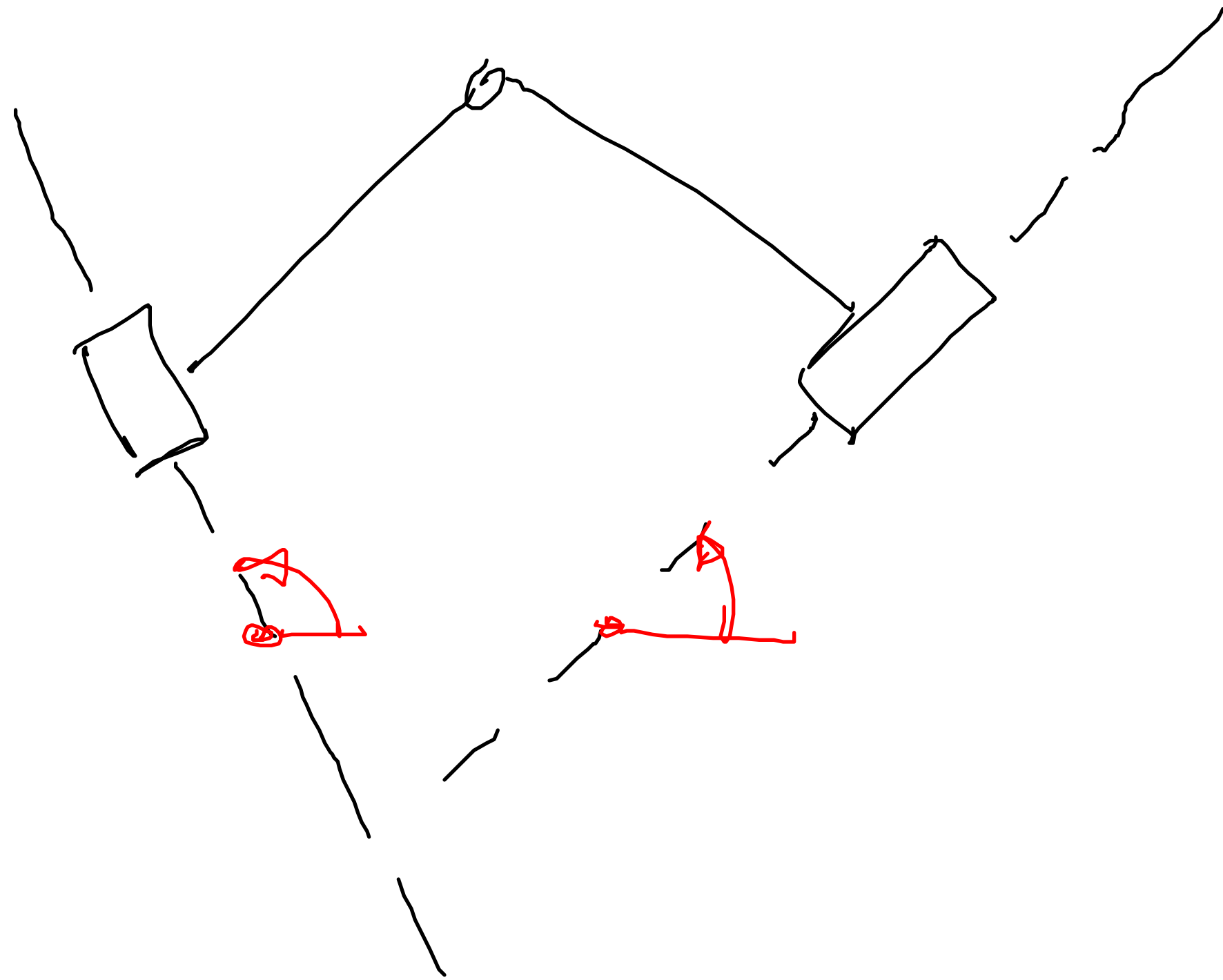
RPR



PRR

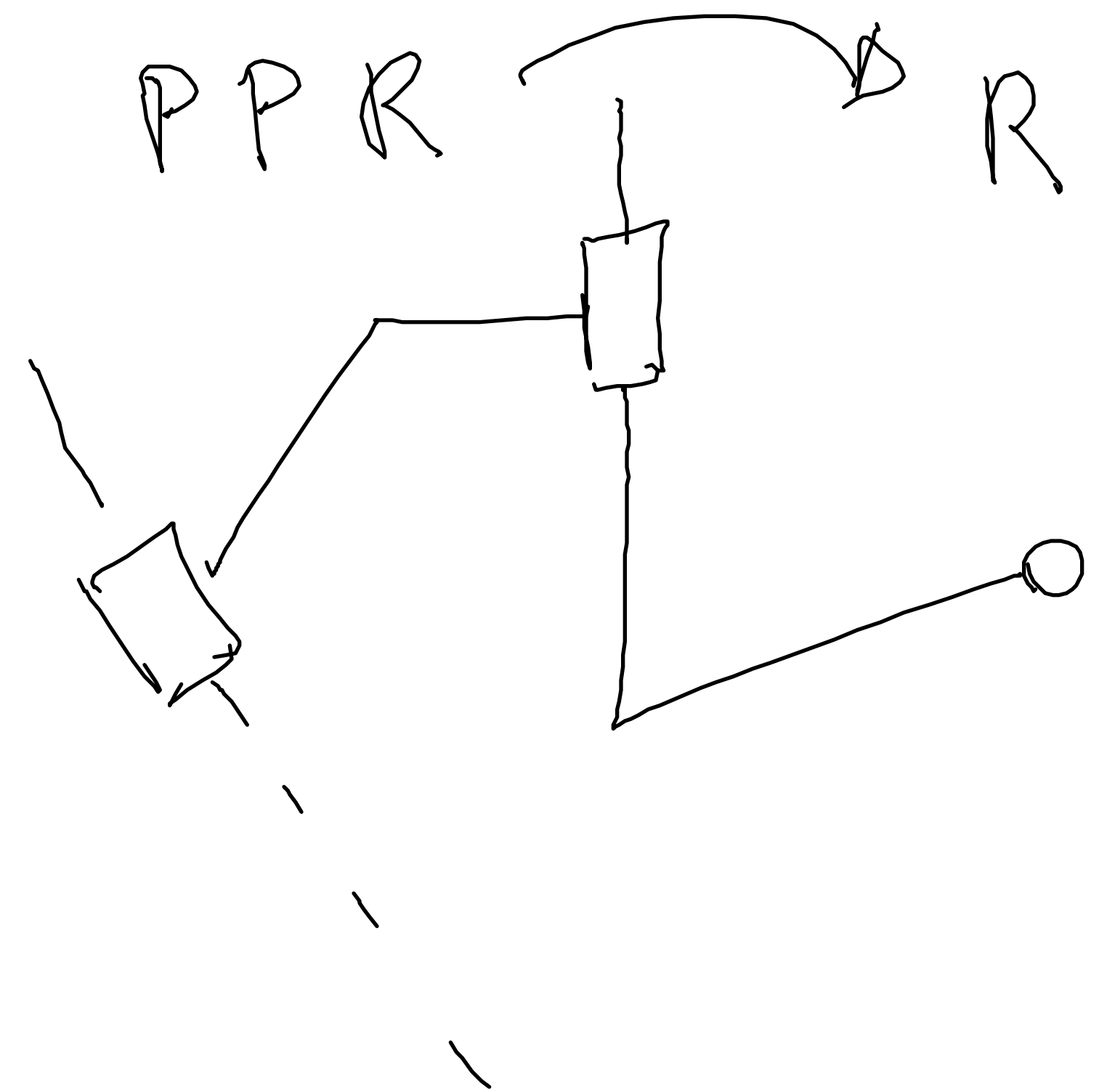


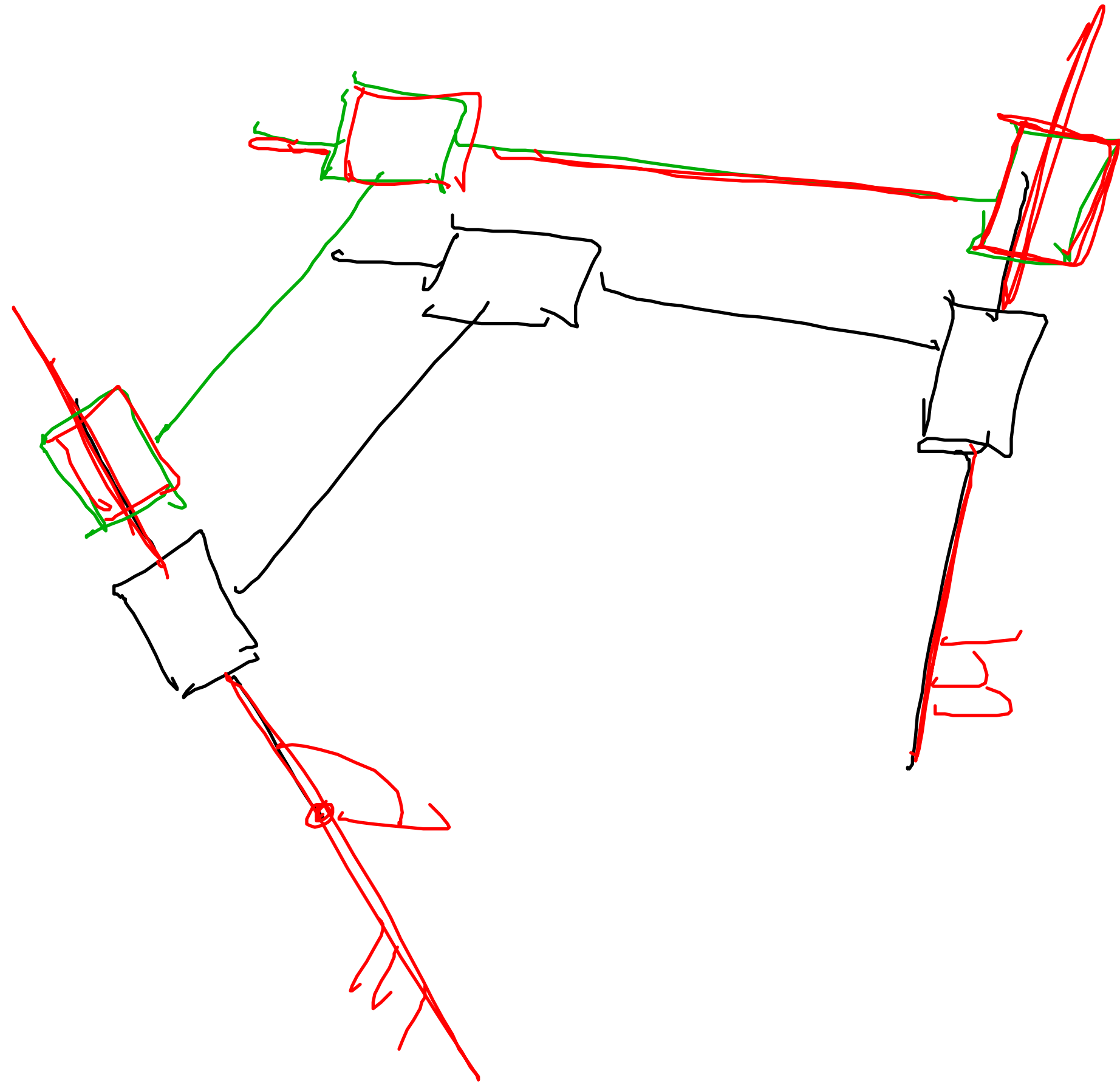
PRP



PPR

RPP





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